

Monitoring Gear Boxes with PeakVue

*Presentation at Niagara Falls
Vibration Institute Chapter*

January 20, 2005

WHAT IS A STRESS WAVE?

Figure 1A



Undelected Plate

Figure 1B



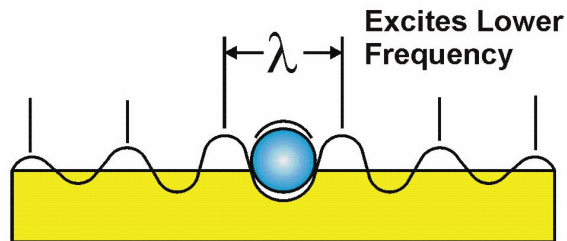
Undelected Plate

$$\lambda = \frac{C}{F}, \text{ Thus } F = \frac{C}{\lambda}$$

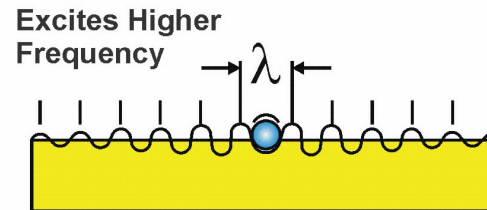
F = Predominant Stress Wave ("PeakVue") Frequency Excited by Impact

C = Speed of sound in the Component which is Impacted

λ = Wavelength of Stress wave Generated by Impact

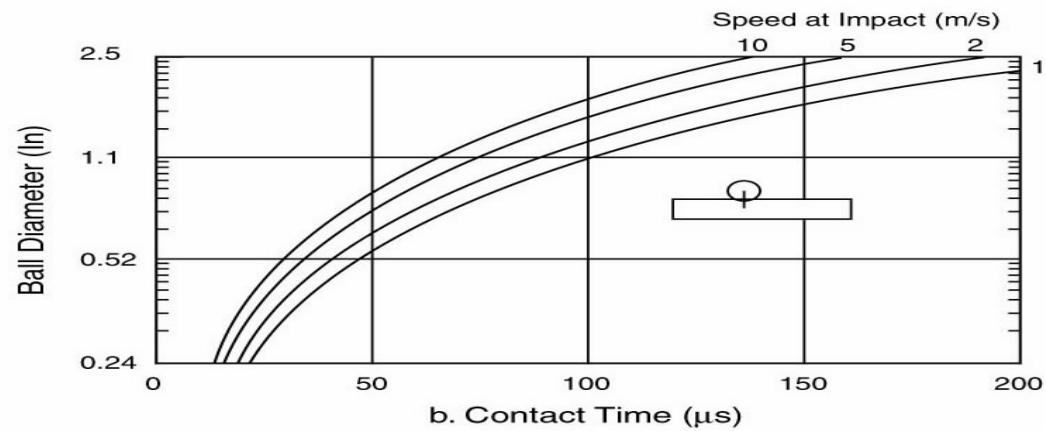
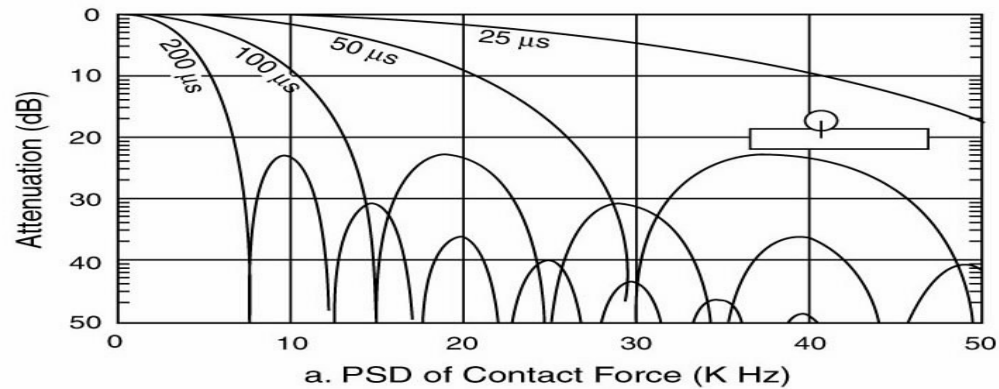


Deflected Plate

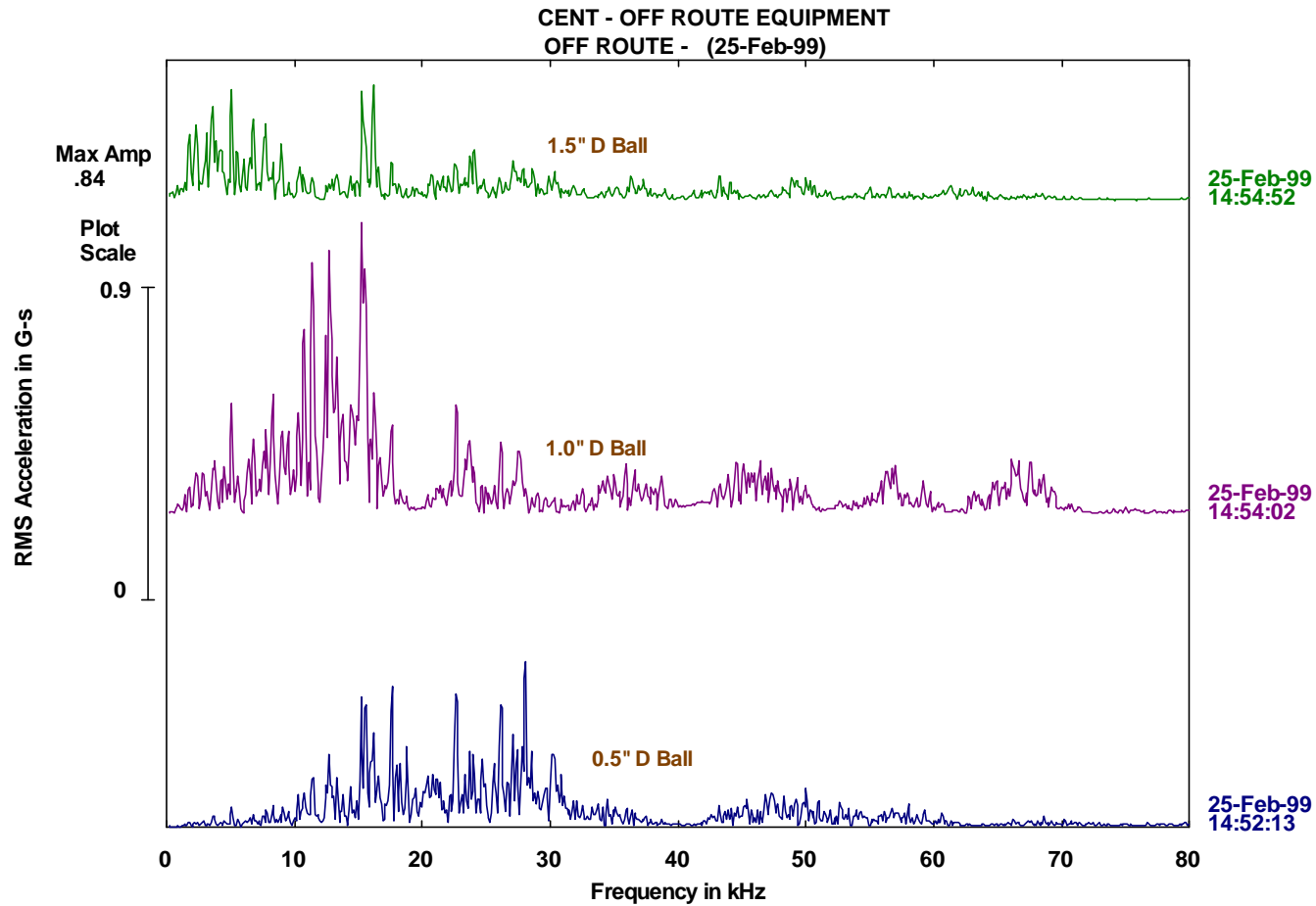


Deflected Plate

Hertz Theory Prediction for Various Size Metal Balls

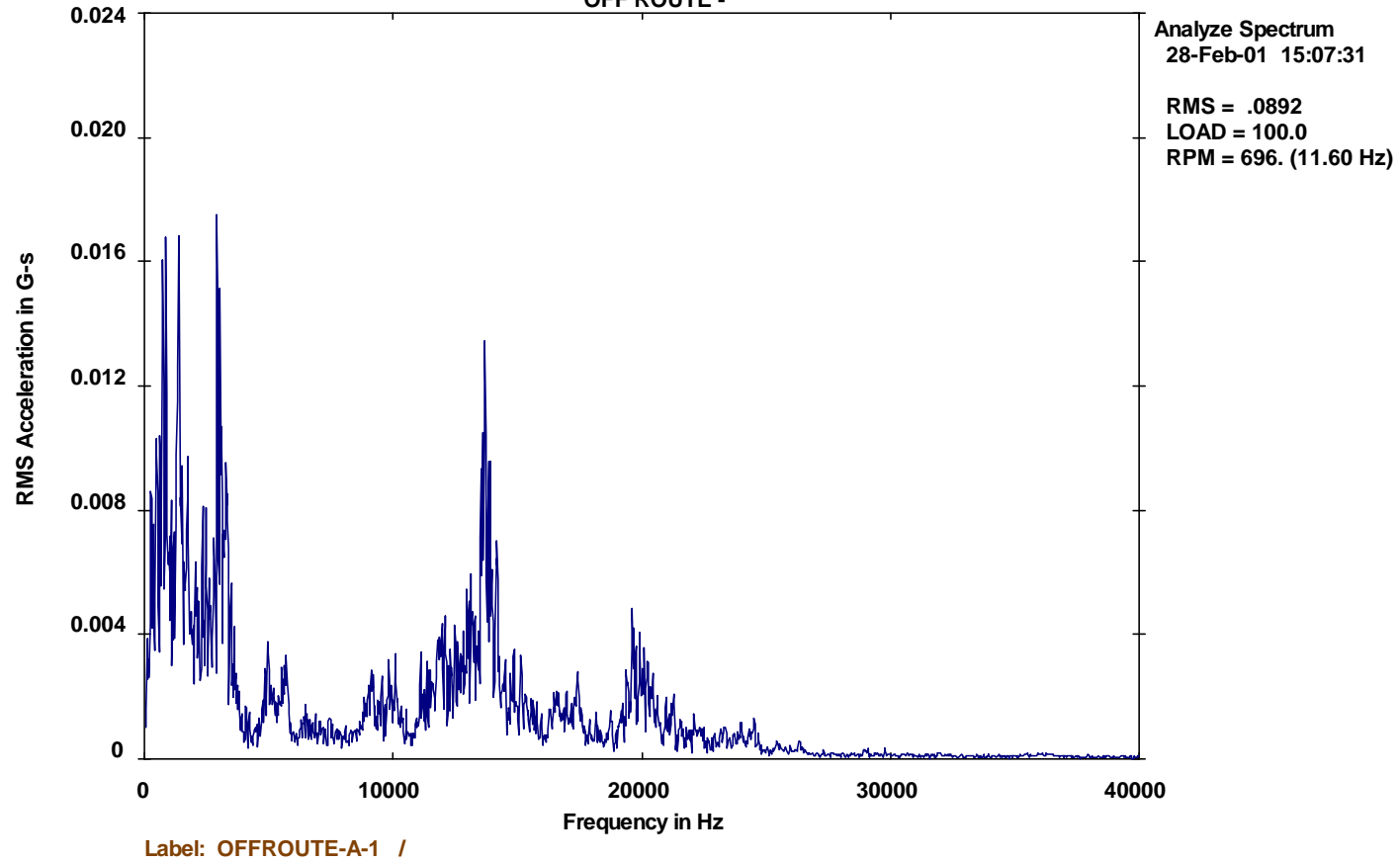


Frequencies Excited by 0.5", 1.0", And 1.5" D Balls Impacting



Impacting and Friction: 1.0 +” D Roller

CENT - OFF ROUTE EQUIPMENT
OFF ROUTE -



Analysis of Stress Waves

- Capture with accelerometer
- High-pass filter
- Capture time block of data
(peak values)
 - a) Spectral Analysis
 - b) Autocorrelation analysis

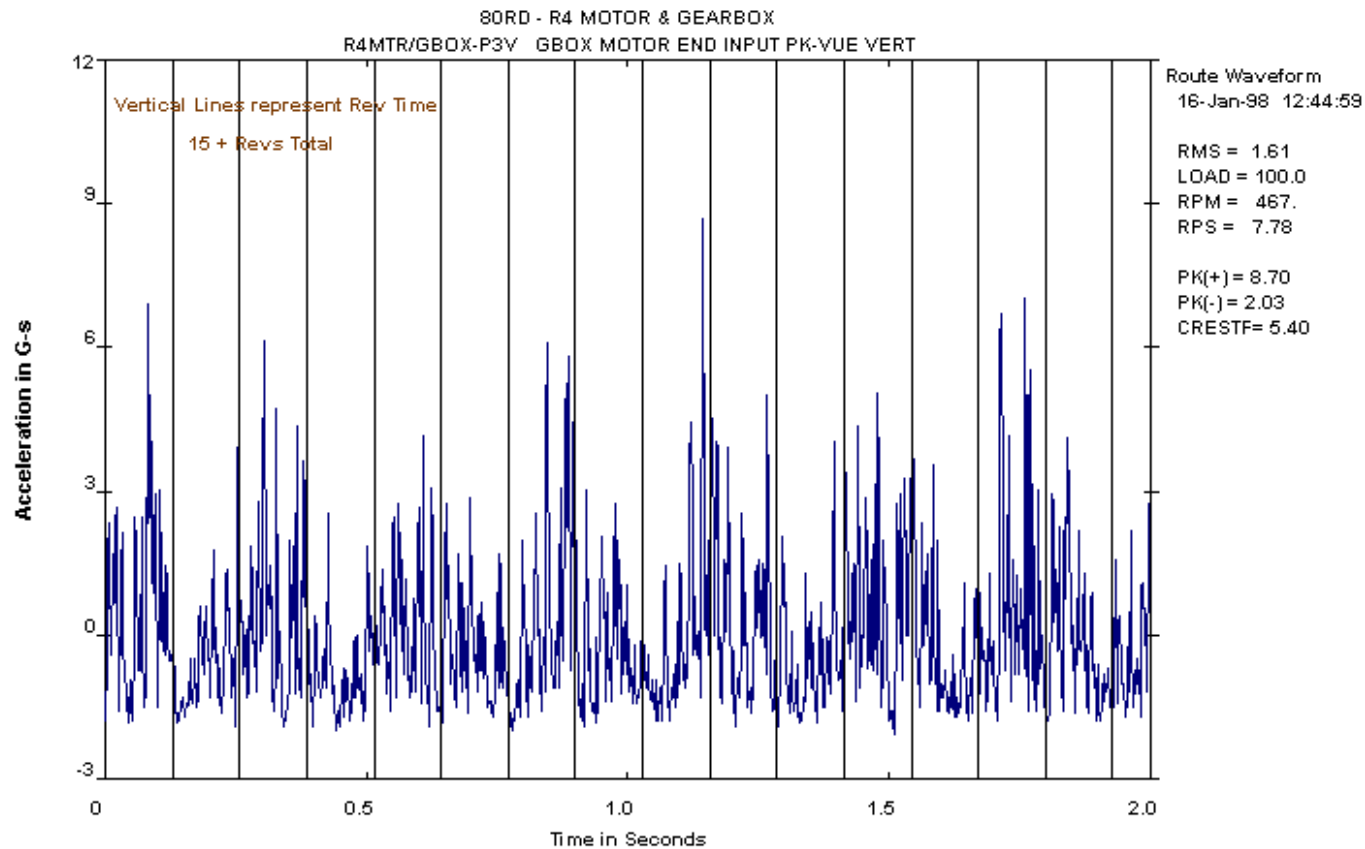
Example Time Waveform

Select F_{\max}

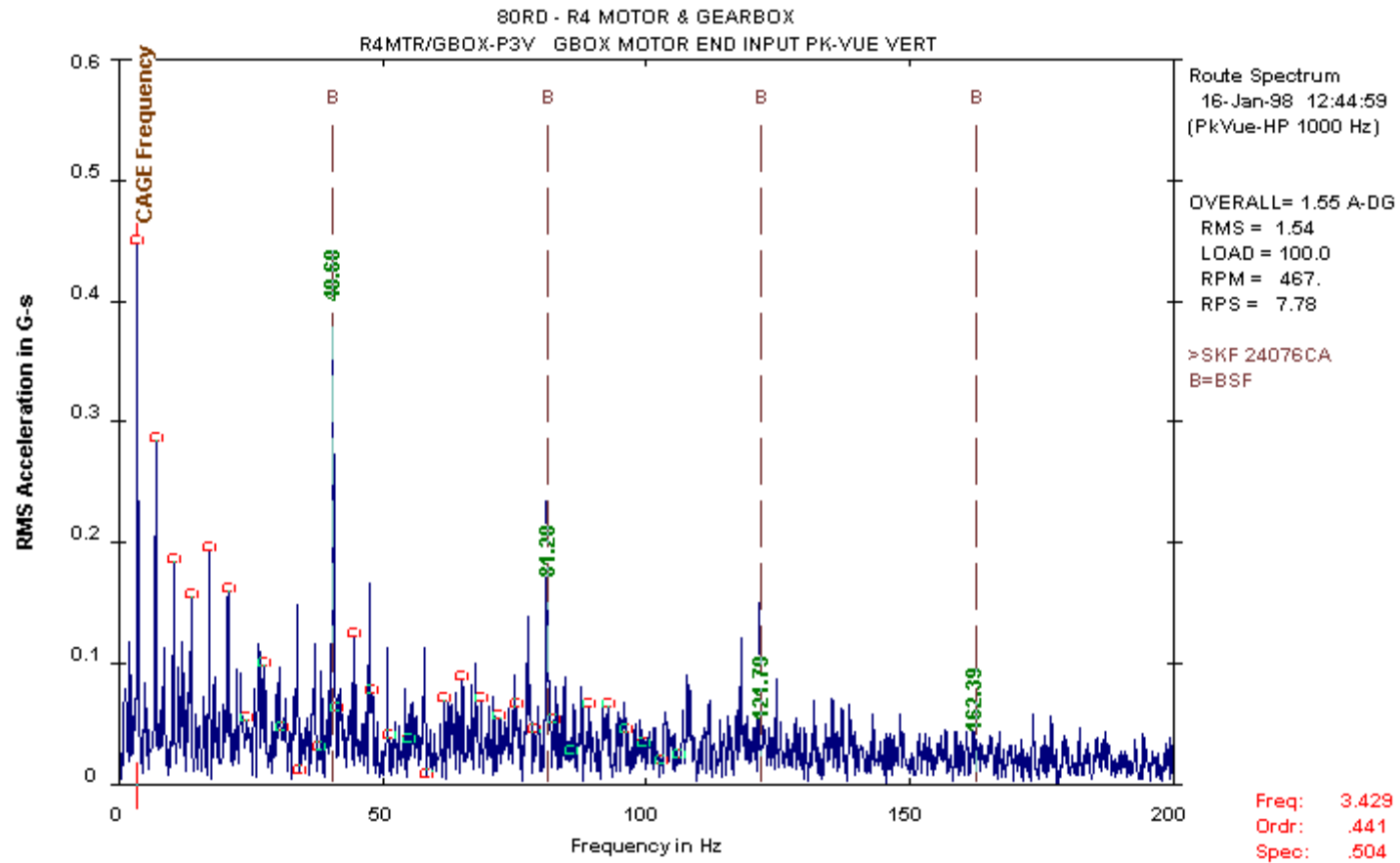
$$\Delta t = 1/(2.56 \hat{F}_{\max})$$

**Sequentially insert in each Δt the
Peak Value observed over that time increment**

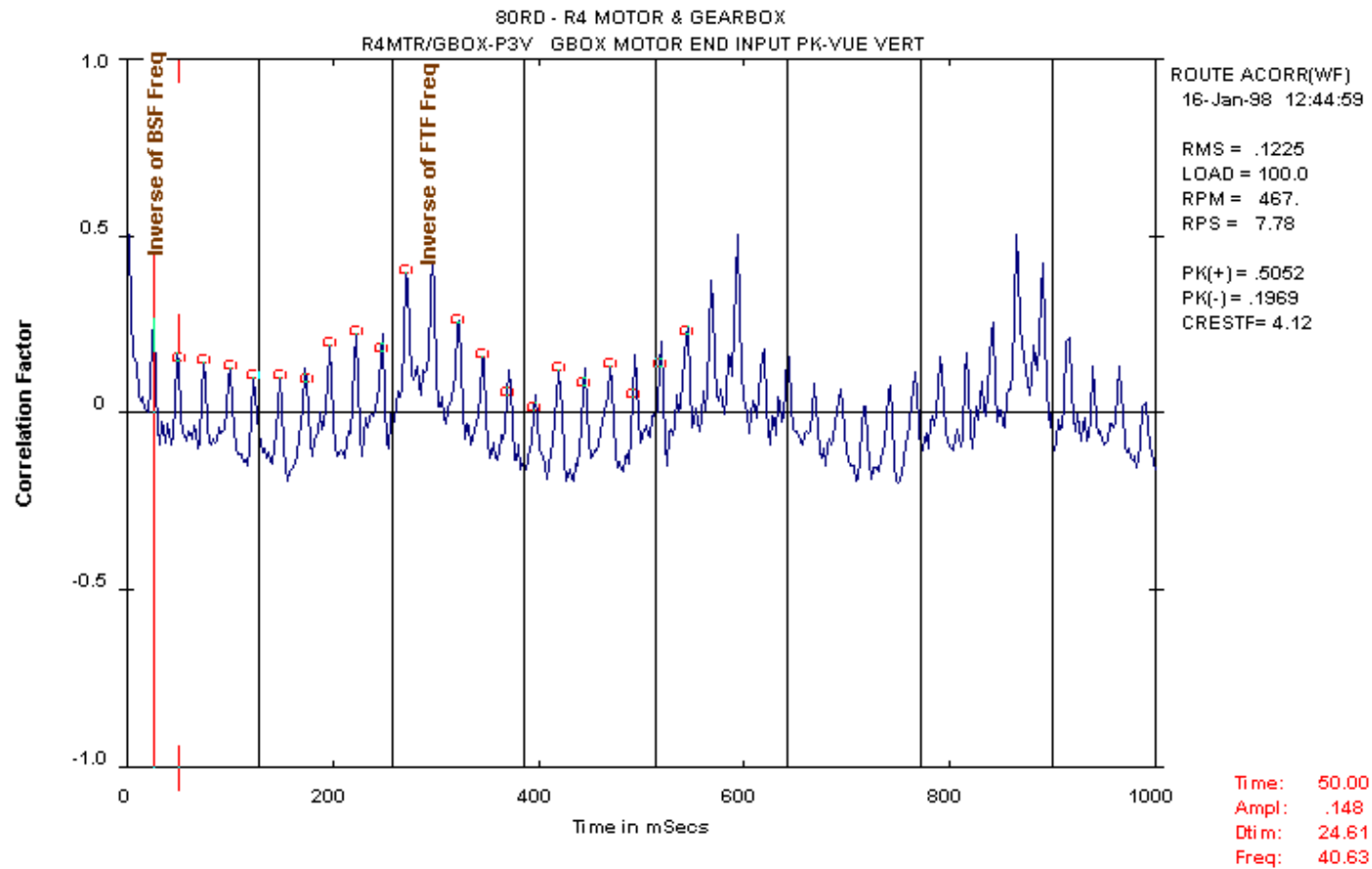
PeakVue Waveform Indicates Defective Rolling Elements (Rollers pass in and out of load zone at rate of Cage Freq.)



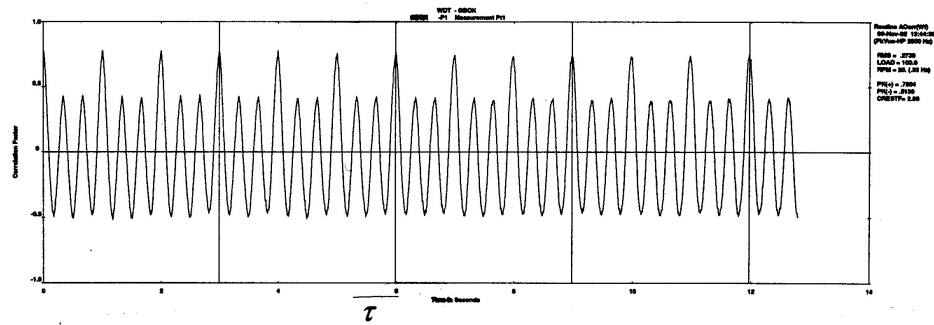
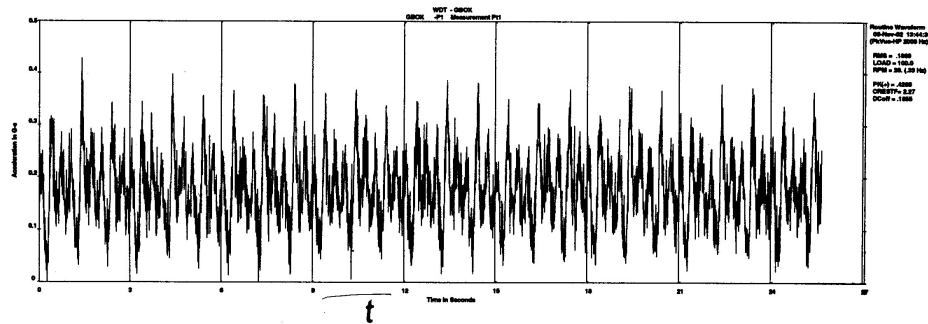
PeakVue Spectrum Derived from PeakVue Waveform (Cage Freq. = 3.43 Hz; BSF = 40.6 Hz)



Autocorrelation Coefficient Function Identifies Dominant Impact Sources in PeakVue Data



Computation of Autocorrelation



$$A(\tau_j) = \frac{1}{A(0)} \sum_{i=1}^{N/2} x(t_i) x(t_i + \tau_j)$$

$$t_i = i\Delta t; i = 1, N$$

$$\tau_j = j\Delta t; j = 1, N/2$$

Measurement Setup Parameters

$$F_{HP} \geq F_{max}$$

- Select F_{max} Based on Fault Frequencies

Bearings: $F_{max} > 4 \times \text{BPFI}$

Gearing: $F_{max} > 2 \times \text{GMF}$

- Select Resolution (# Lines) Based on Lowest Fault Frequency

Bearings: Cage

Gearing: Slowest shaft for gear pair in Mesh

Measurement Setup Parameters (cont.)

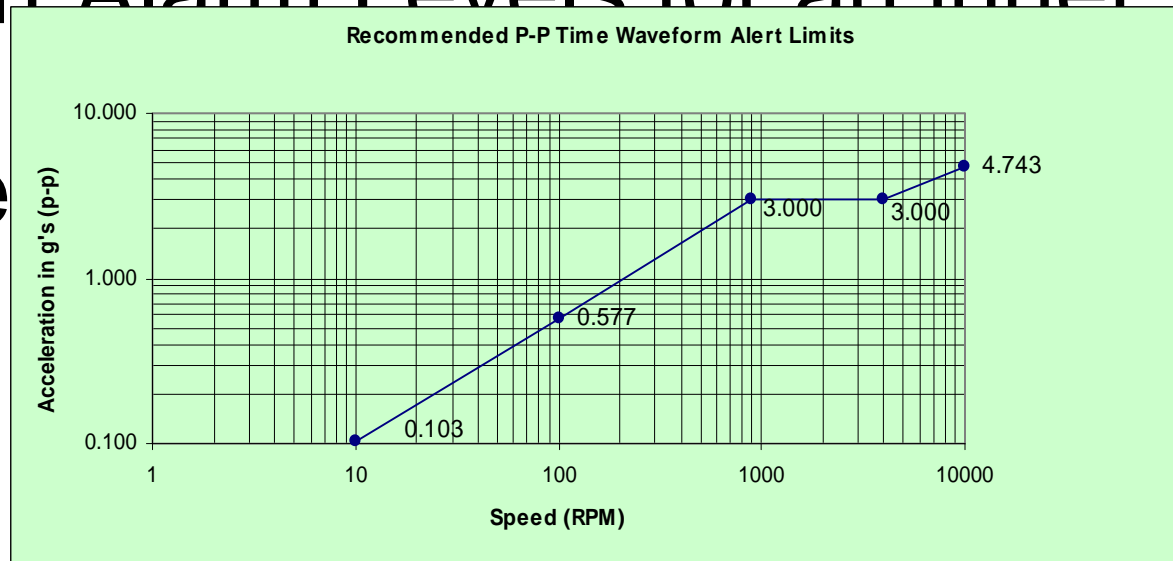
- Cage - requires 12+ shaft revs

$$\# \text{ Revs} = \frac{\# \text{ lines}}{F_m \text{ in orders}}$$

- Shaft - Requires 5+ shaft revs
- F_{HP} (High-Pass Filter)
 - Same (highest) over a machine (structure with continuous housing).
 - F_{HP} greatest for bearings or gears on machine
 - F_{max} can be varied, but same F_{HP} must be used on all points on component (i.e., throughout Gearbox)

Guidelines for setting Pk-Pk PeakVue Time Waveform Alert Alarm Levels for an inner race

(See



(rm)

$$g's = \left(\frac{\text{RPM}}{900} \right)^{0.75} \times 3$$

for RPM < 900

$$g's = 3 ,$$

for 900 < RPM ≤ 4000 ,

$$g's = \left(\frac{\text{RPM}}{4000} \right)^{0.5} \times 3$$

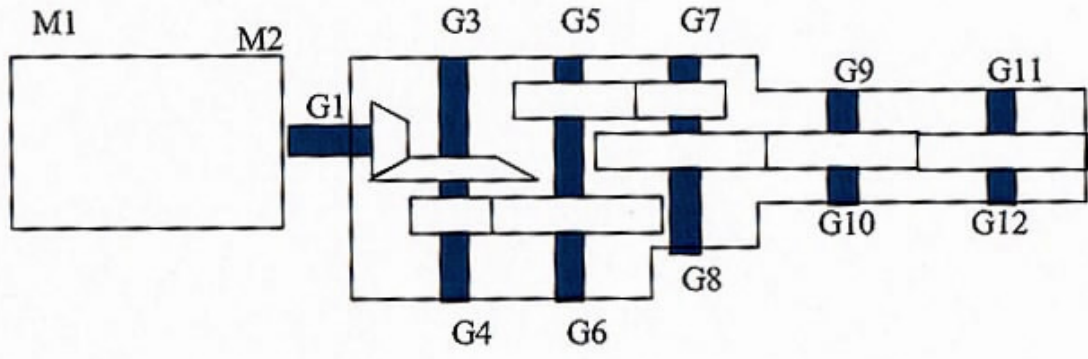
for 4000 < RPM ≤ 10000 ,

$$g's = 5 ,$$

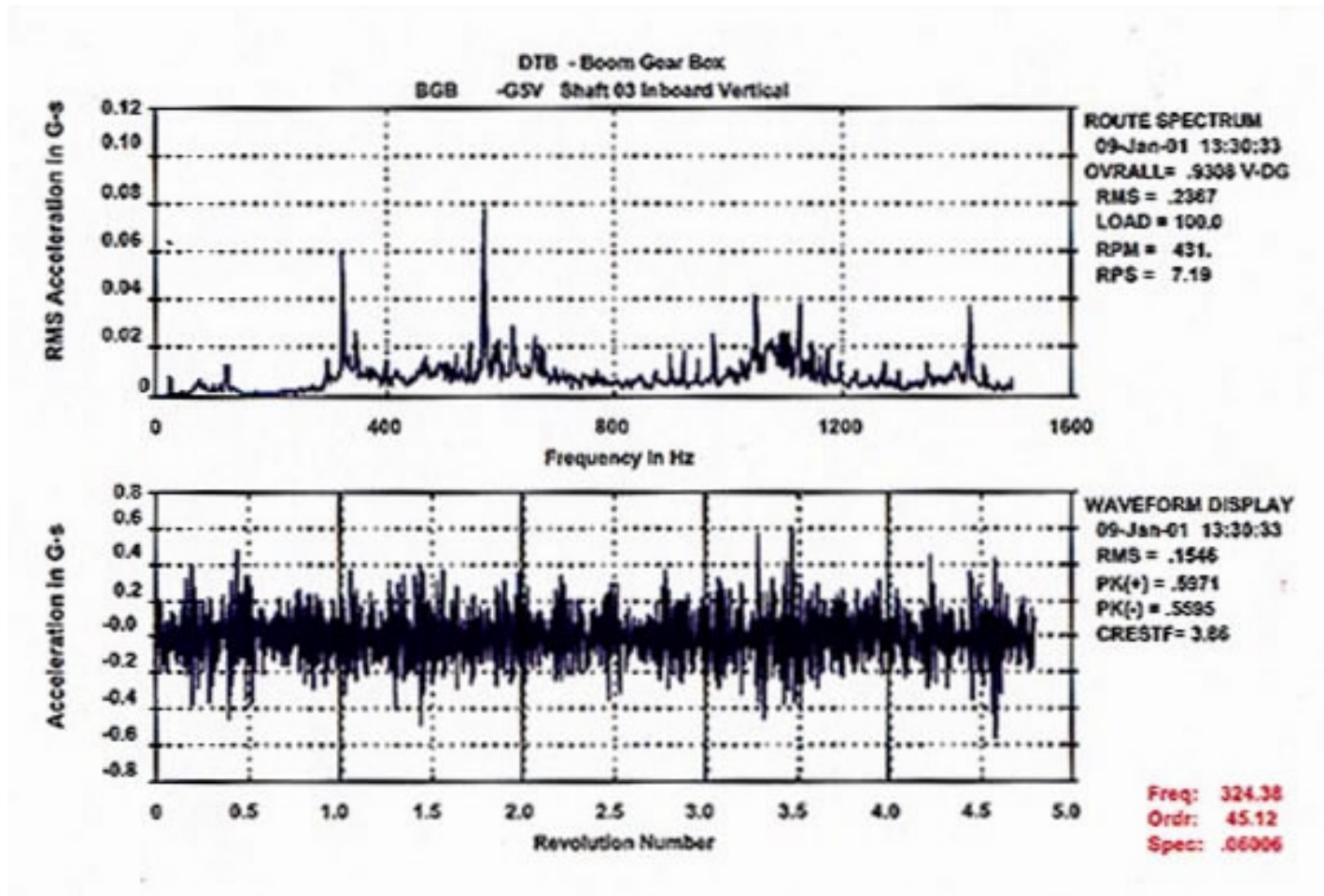
for RPM > 10000 ,

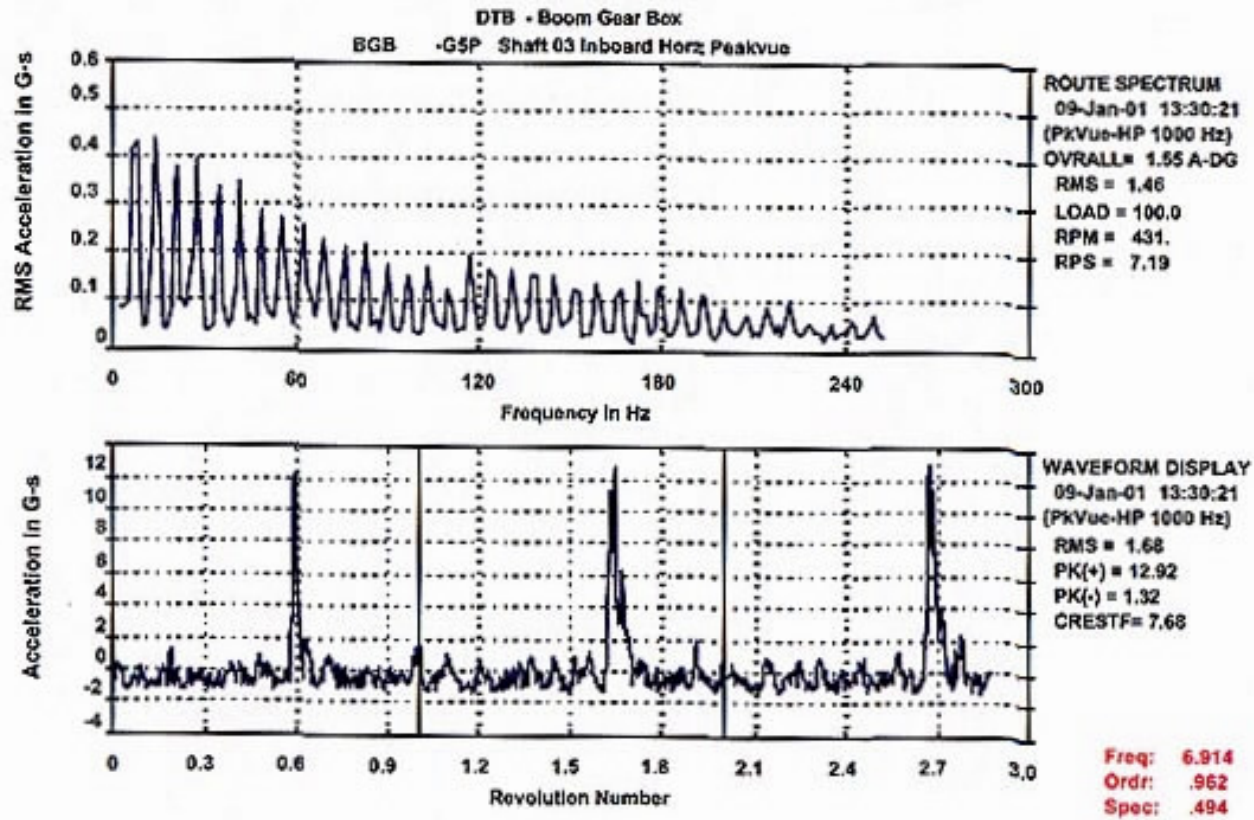
Gear Box

- Case Study # 1
 - A) Cracked Tooth on post rebuild gear box
 - B) Cracked Tooth on Precision Tension Bridle

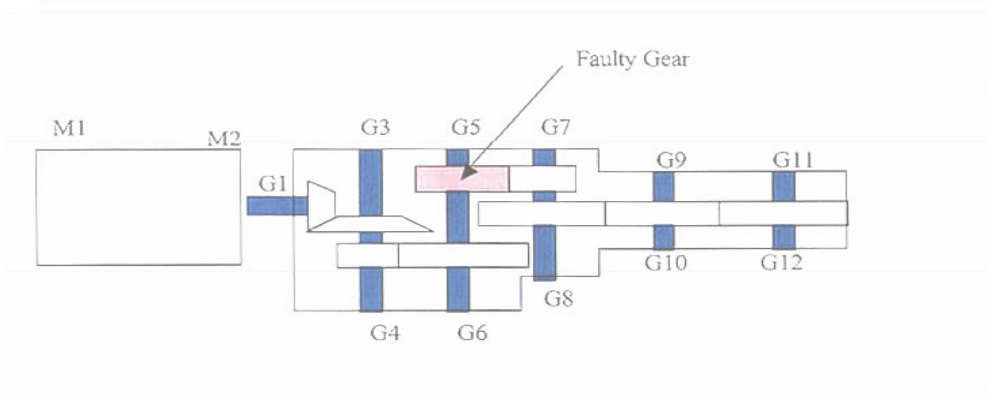


Fault under Meas Point G5

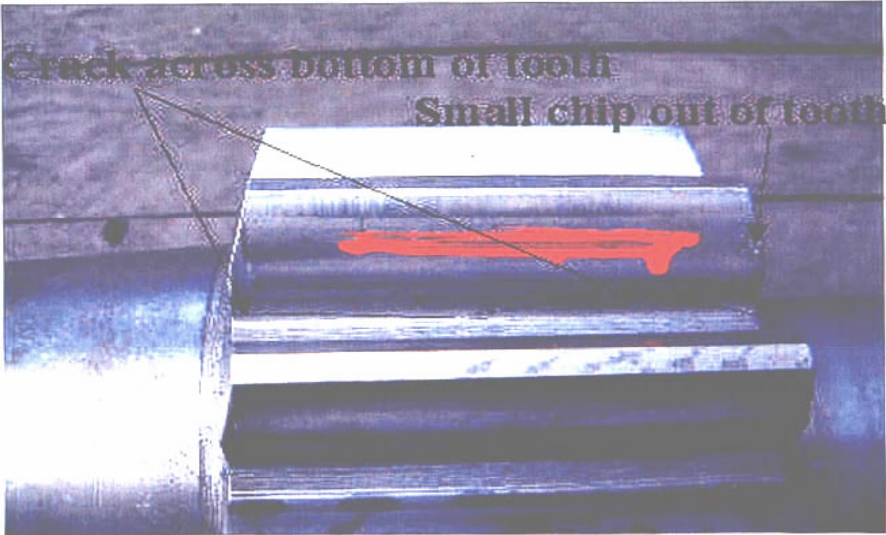




Cracked Tooth Highlighted



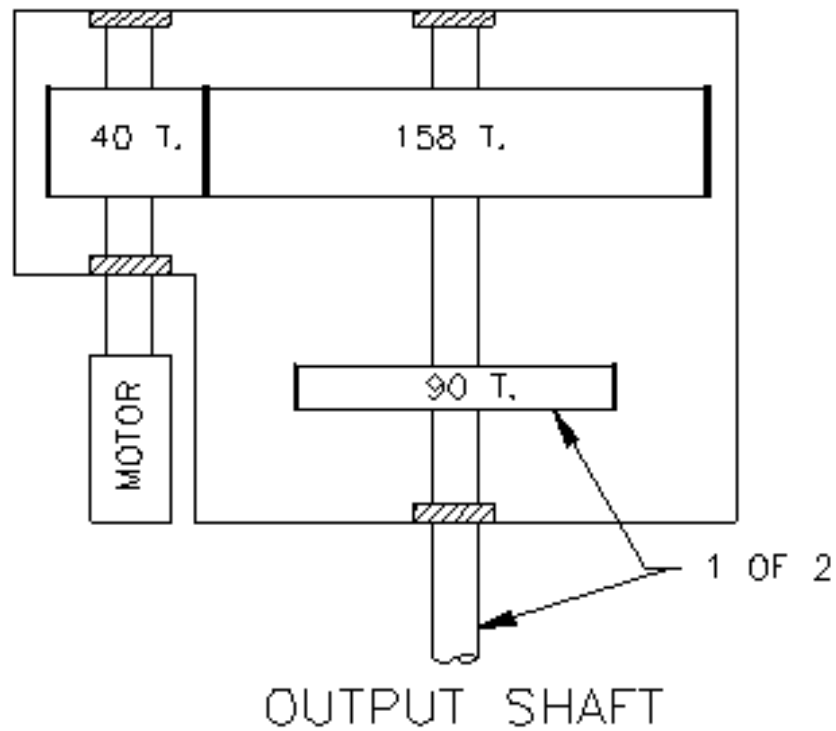
Picture of Shaft



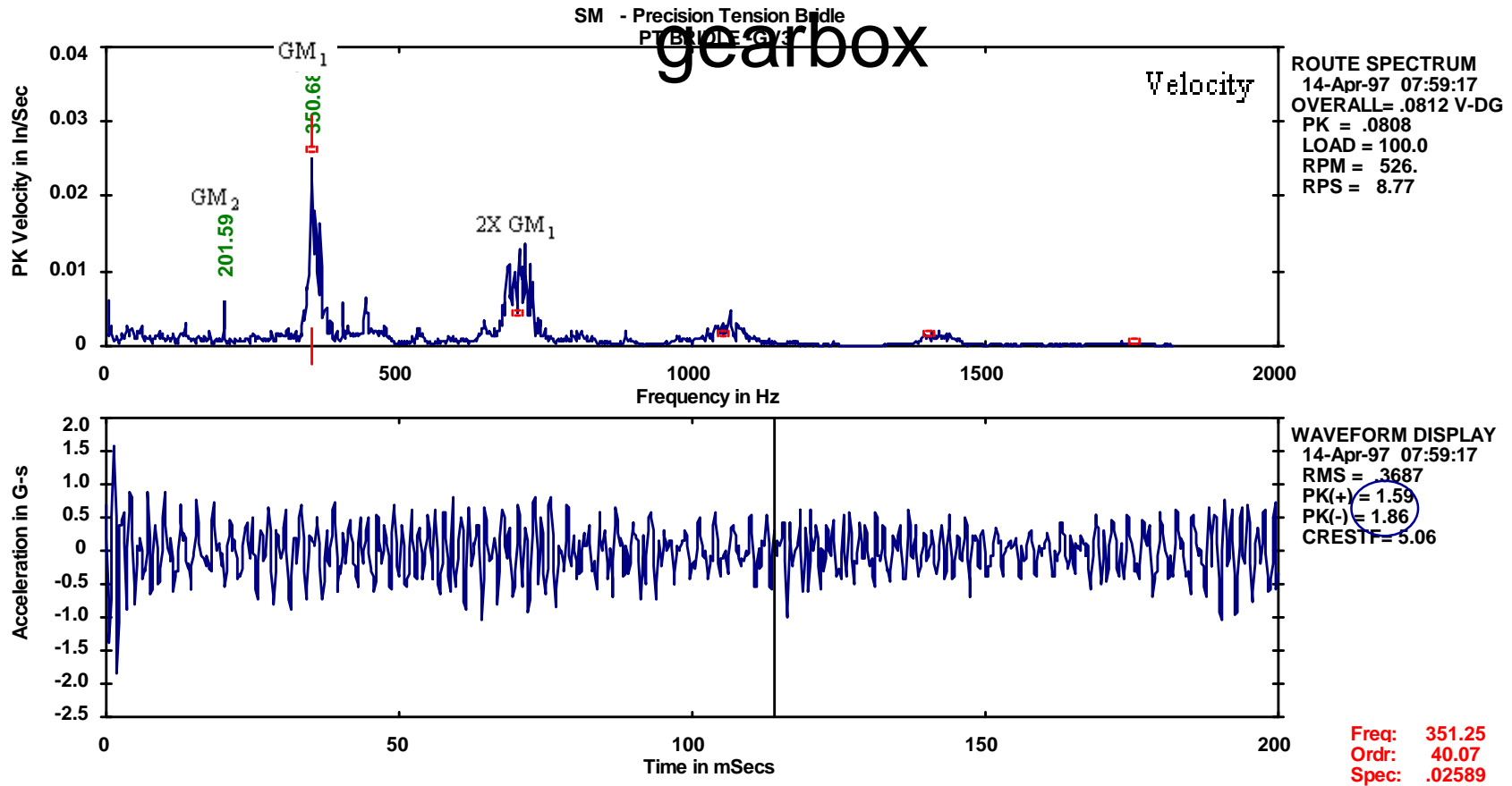
Cracked Teeth in Precision Tension Bridle GearBox

- Based on Pk-Pk Level of 41 g's in TWF
 - Pronounced Impact Pulses in TWF
- (2/Rev)
- No Real Indication of Problem in
Vibration Data

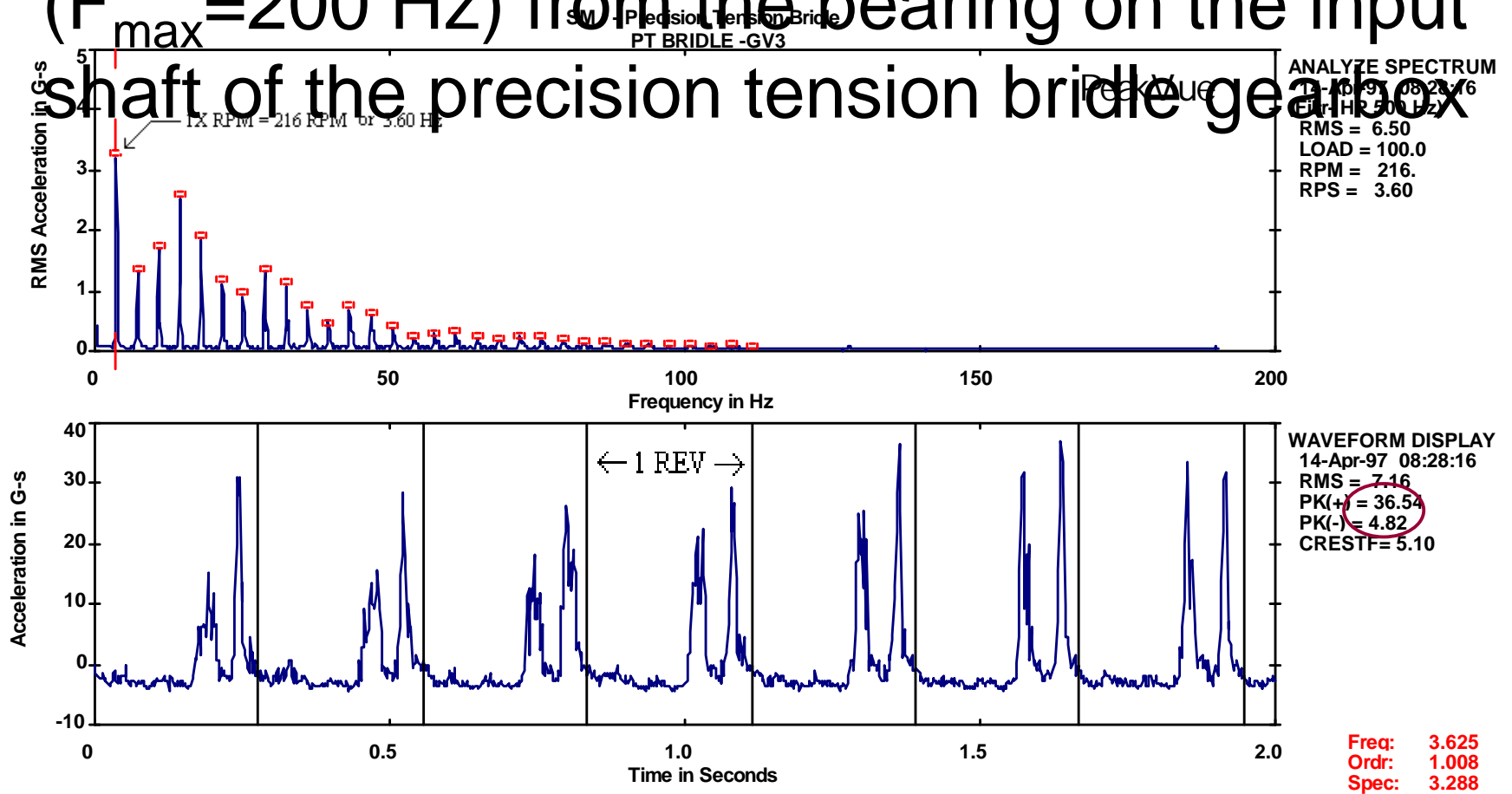
Plan view of precision tension bridle gearbox (single speed reduction with two output shafts)



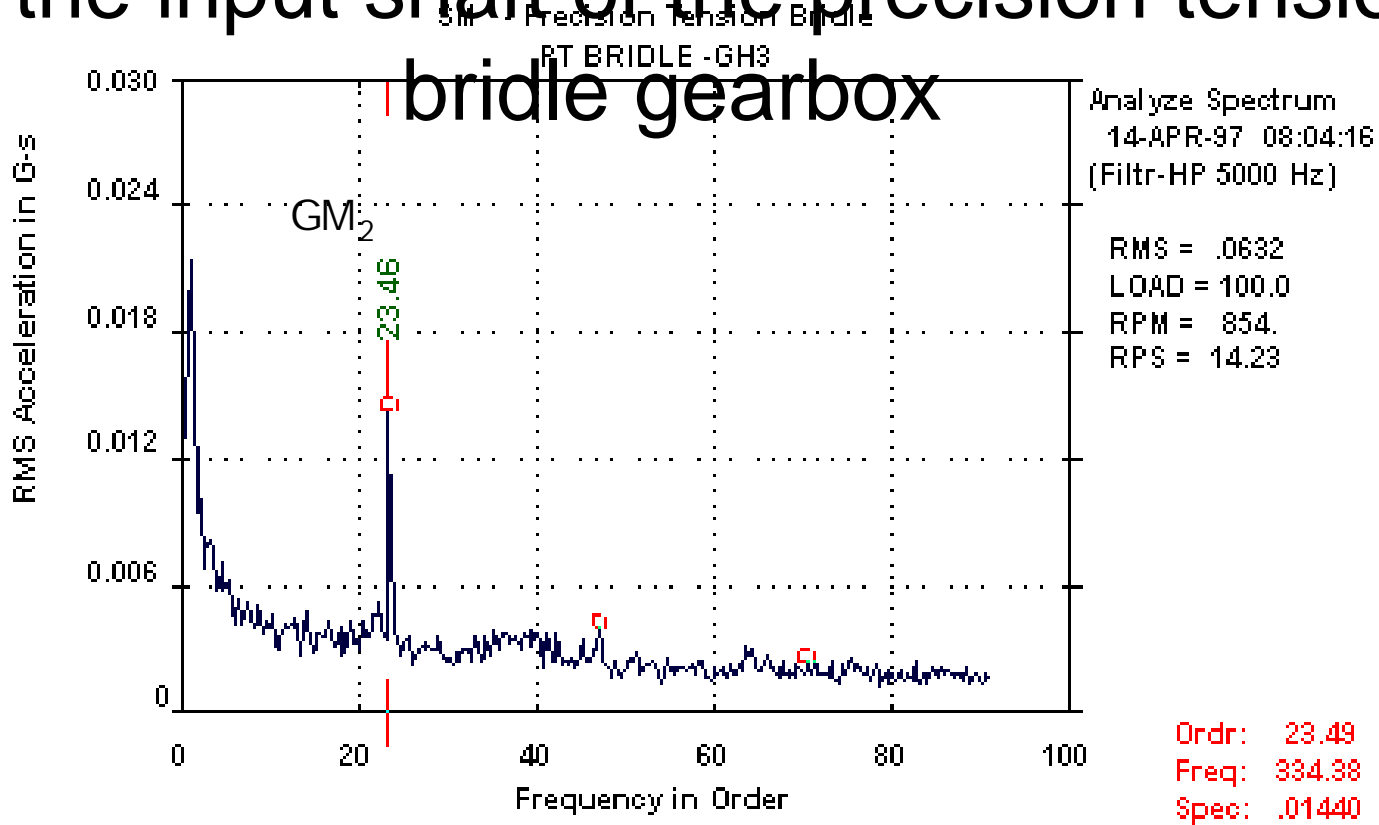
velocity spectral and acceleration waveform data (Fmax=2000 Hz) from the bearing on the input shaft of the precision tension bridle



PeakVue spectral and waveform data ($F_{max} = 200$ Hz) from the bearing on the input shaft of the precision tension bridle gearbox

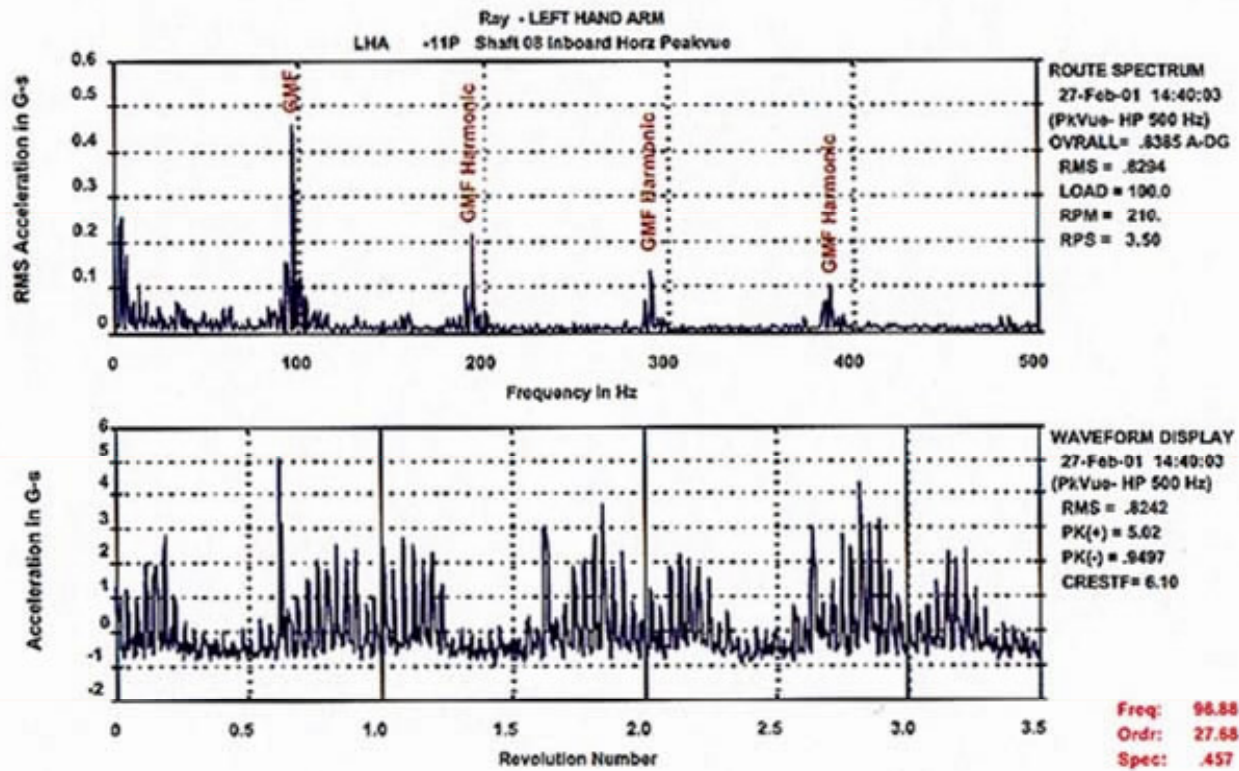


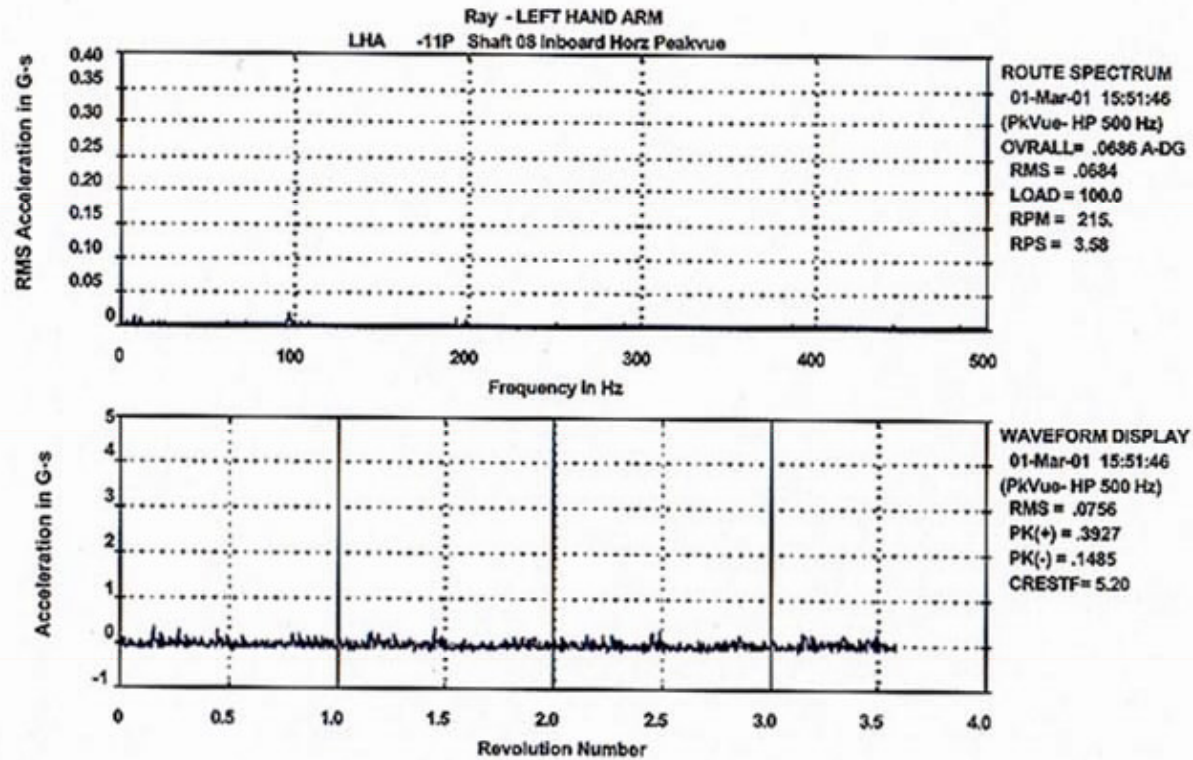
PeakVue spectral and (Fmax=100 Hz but with a 5000 Hz HP filter) from the bearing on the input shaft of the precision tension



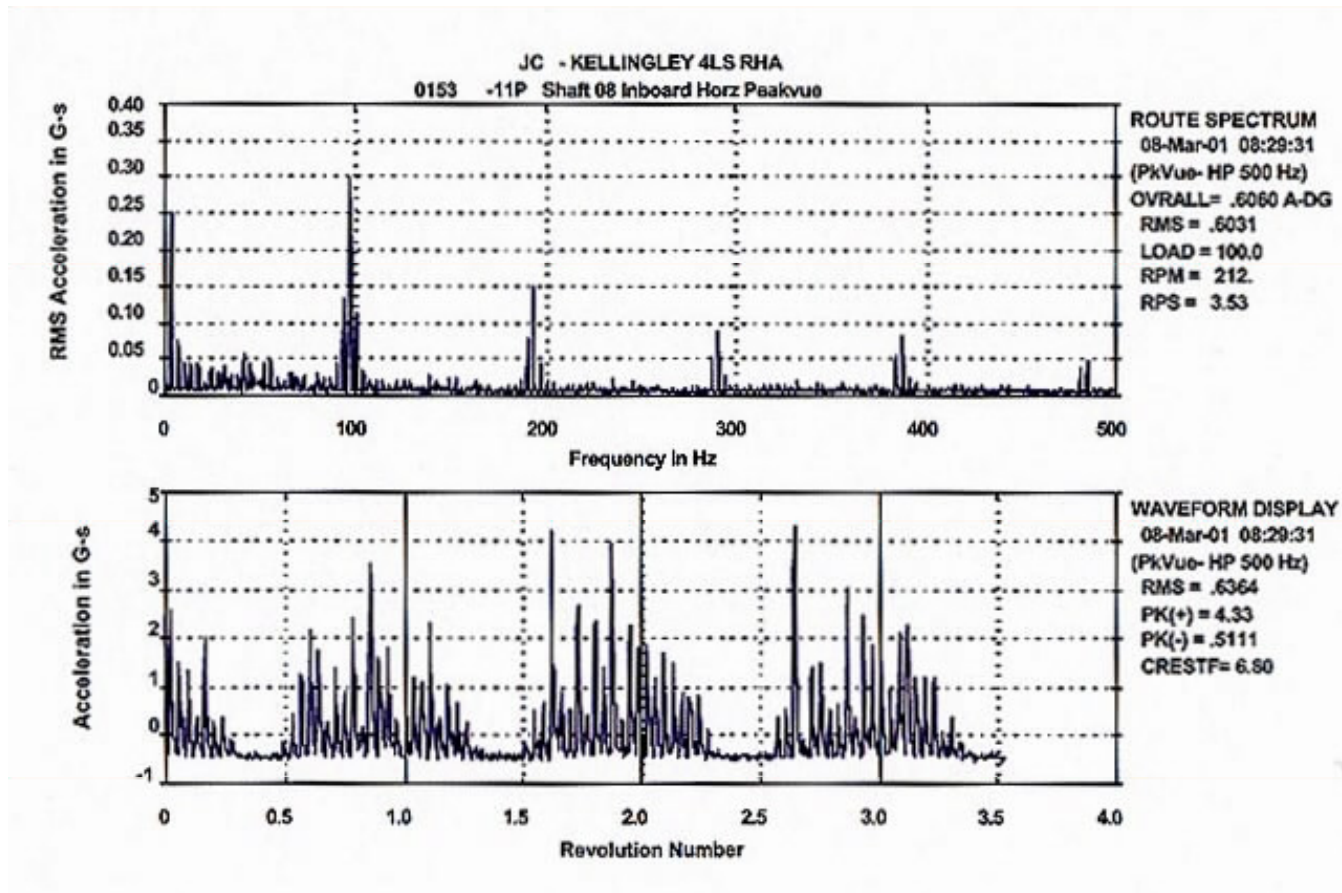
Gearbox

- Case Study # 2
 - Eccentric gear on post rebuild gear box



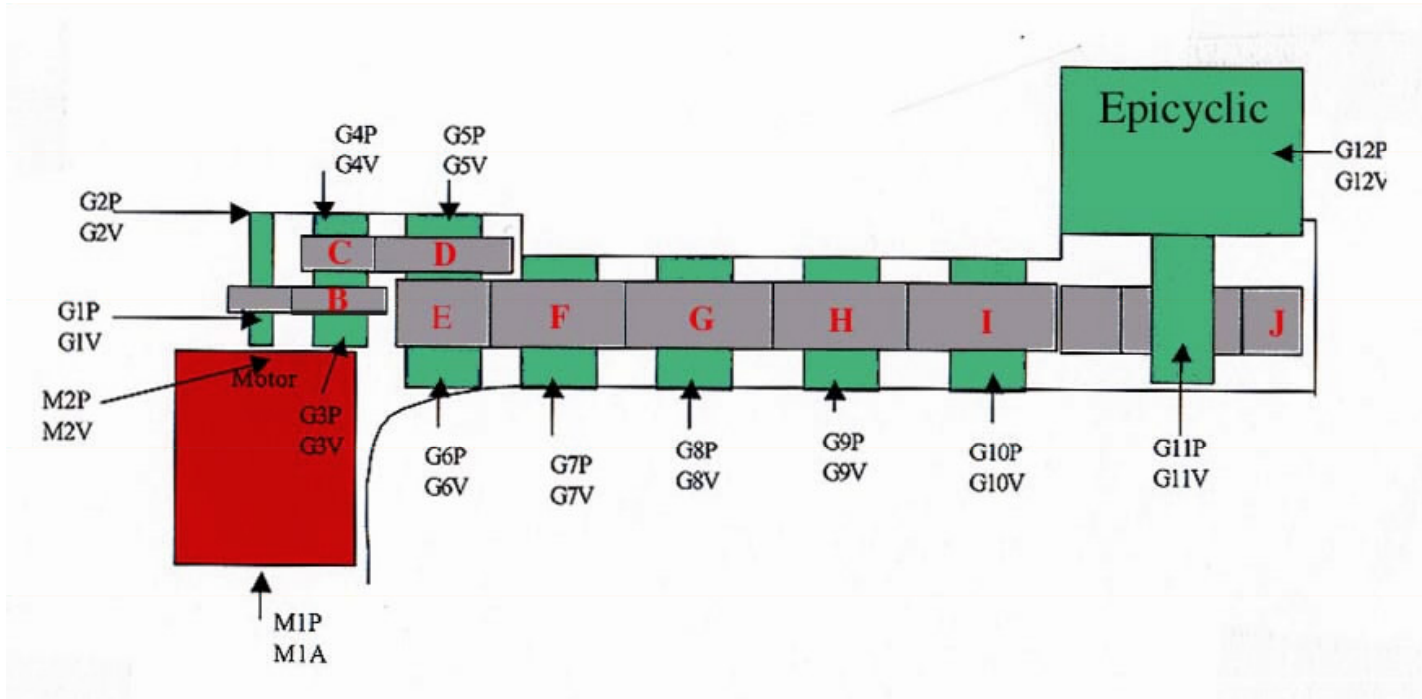


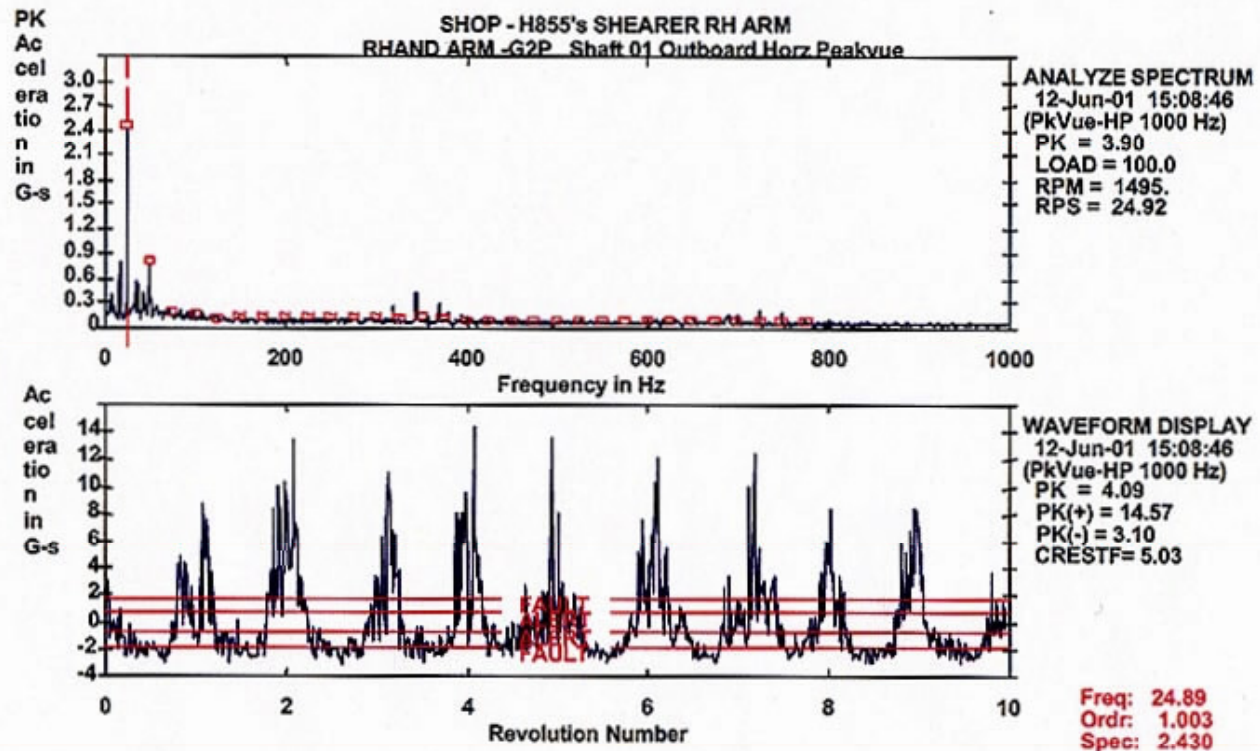
Defective Gear Placed in Separate Gear Box

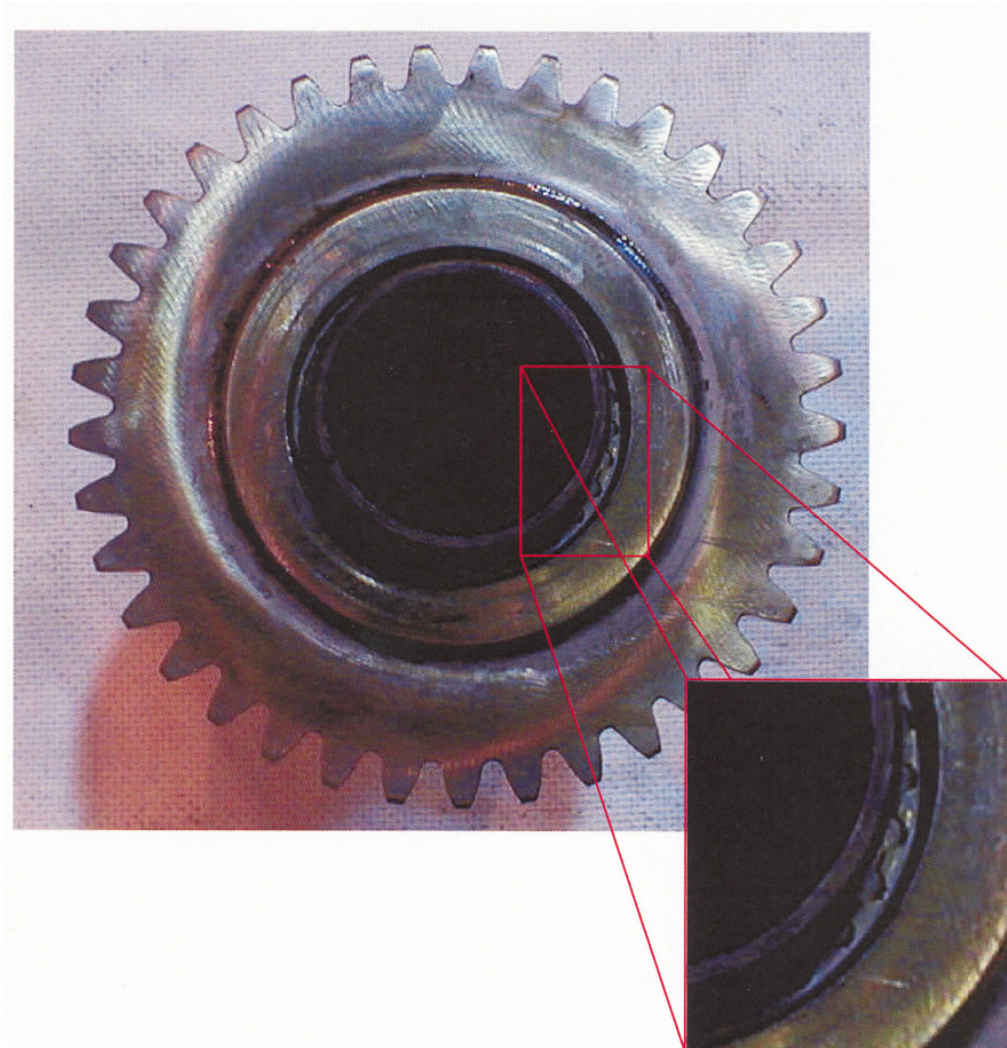


Gear Box

- Case study #3
 - Worn spline on post rebuild gear box



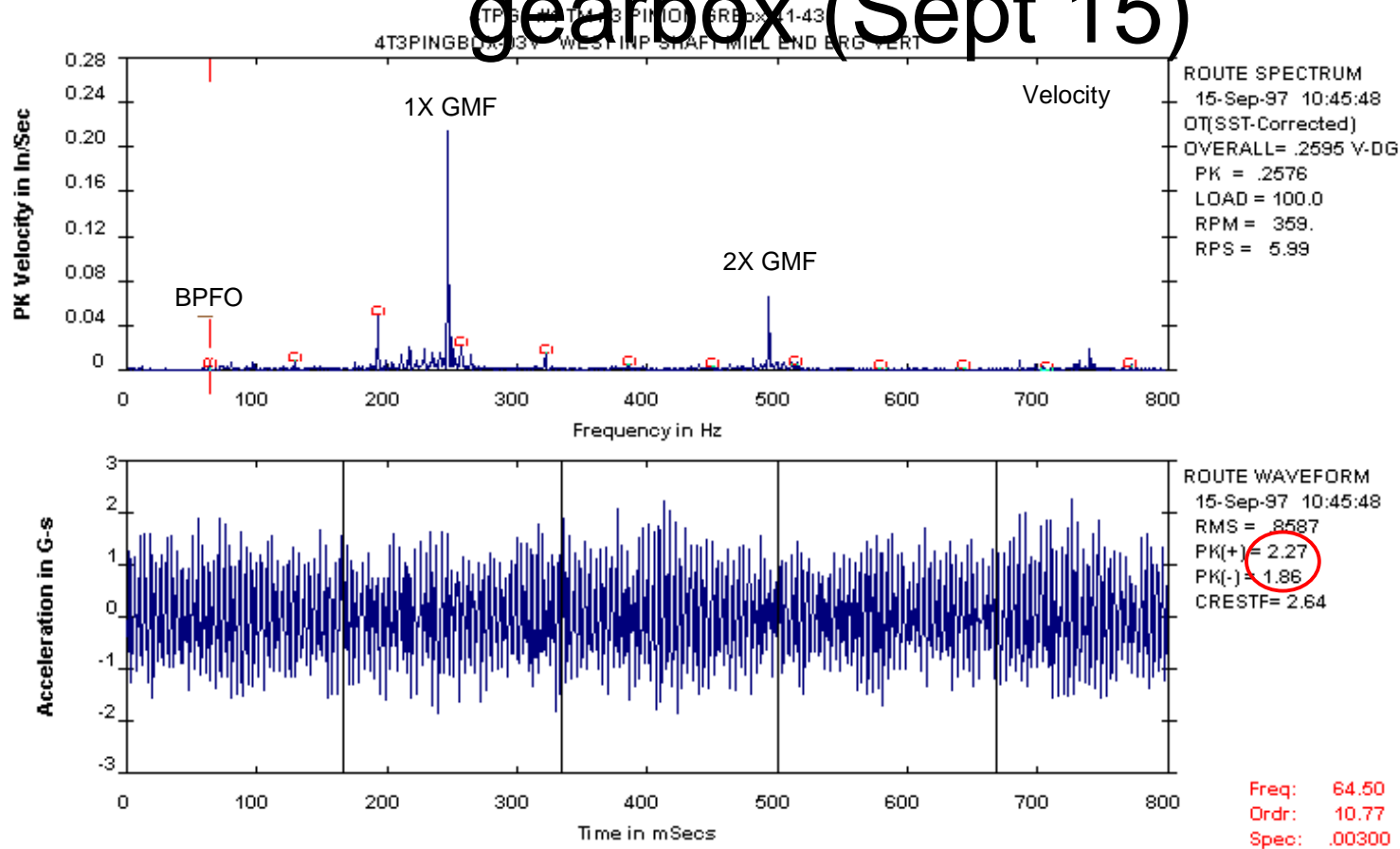




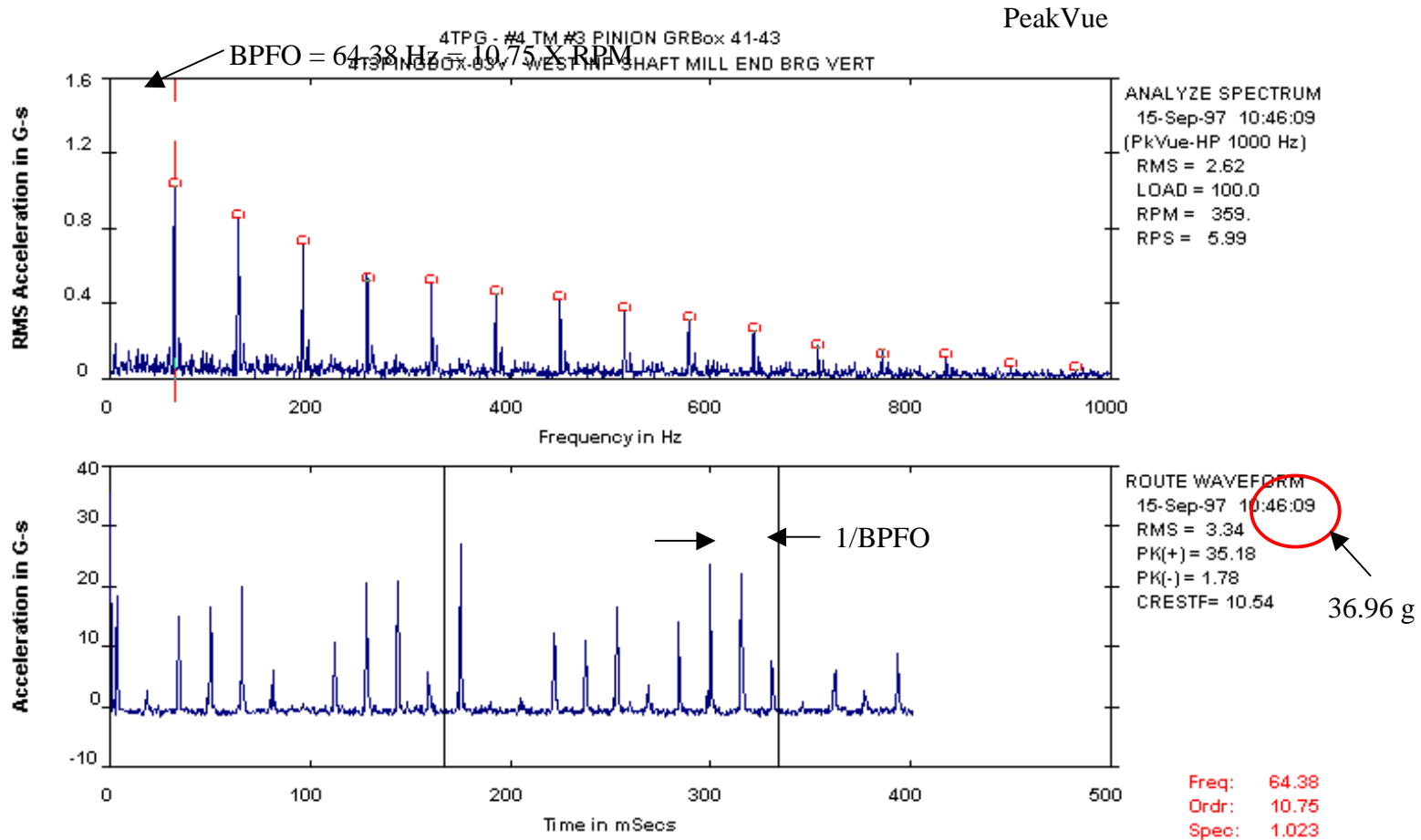
Bearing-Outer Race

- Case Study #4
- BPFO in Pinion Stand Gearbox
 - Speed of shaft=360 RPM
 - Peak g-level=37 g's
 - Fault=6.3 g's

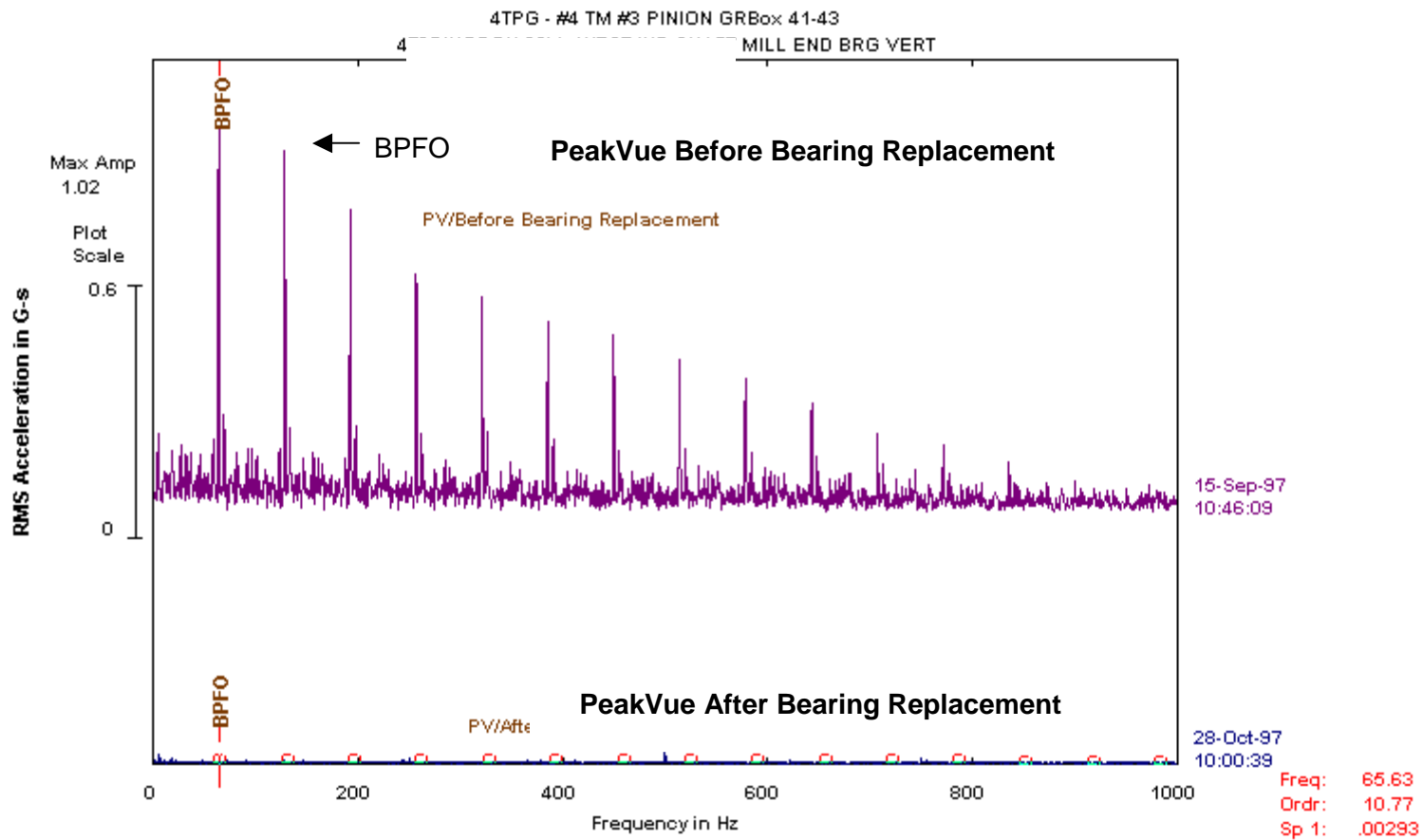
Velocity spectra and acceleration waveform data (Fmax=800 Hz) from the bearing on the input shaft of the gearbox (Sept 15)



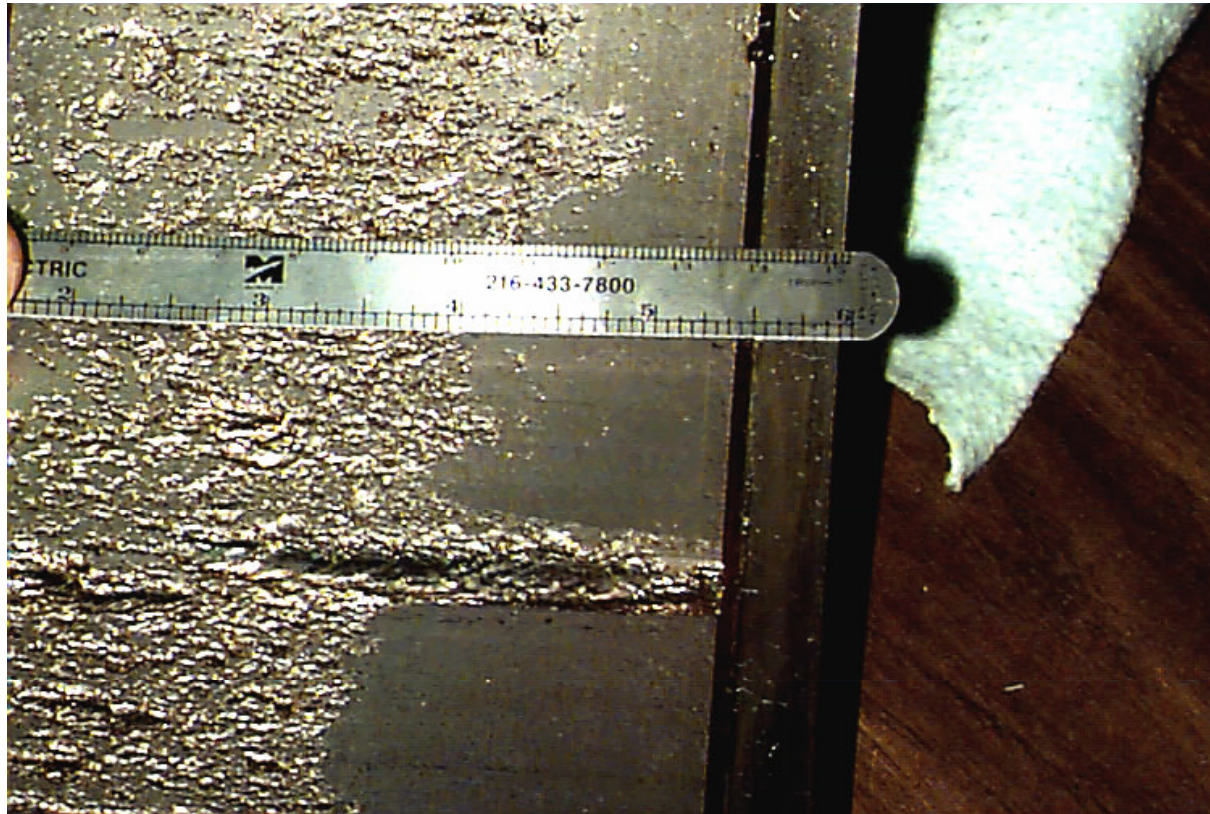
PeakVue spectral and waveform data (Fmax=1000 Hz) from the bearing on the input shaft of the gearbox (Sept 15)



Peakvue spectral and waveform data (Fmax=1000 Hz) from the bearing on the input shaft of the gearbox before and after bearing replacement



Closeup picture of the outer race of the defective bearing showing significant spalling over an area of 5 in. x 5 in.

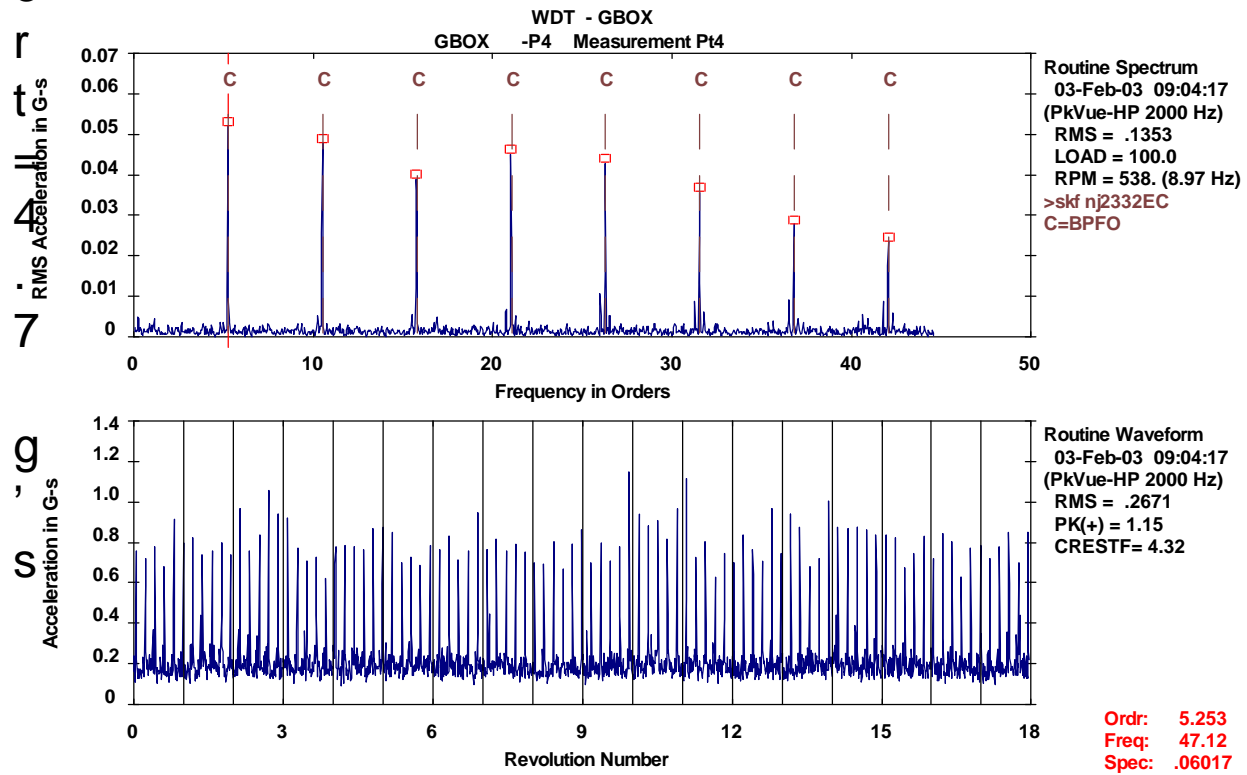


Bearing Outer Race

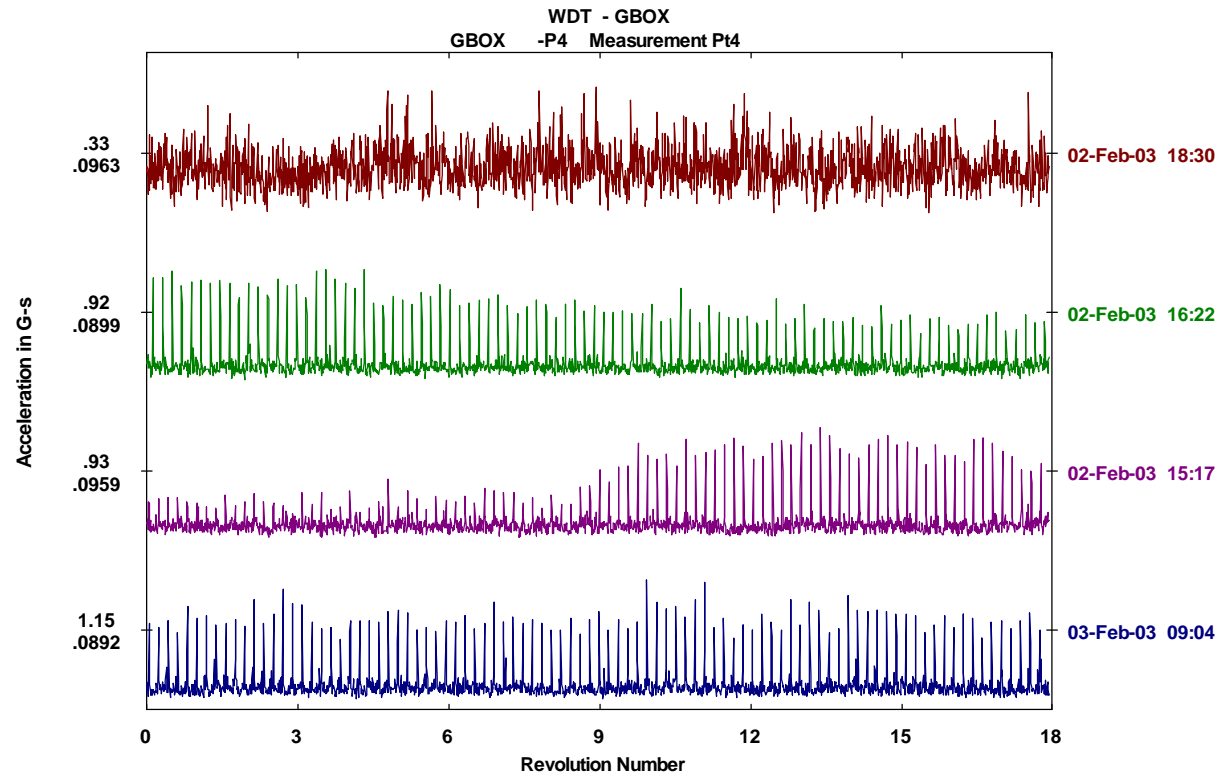
- Case Study #5 BPFO
 - **Early stage fatiguing**
 - **Shaft speed=650 RPM**
 - **Alert=4.7 g's**

A
l
e
r
t
4
7

Alert=4.7 g's



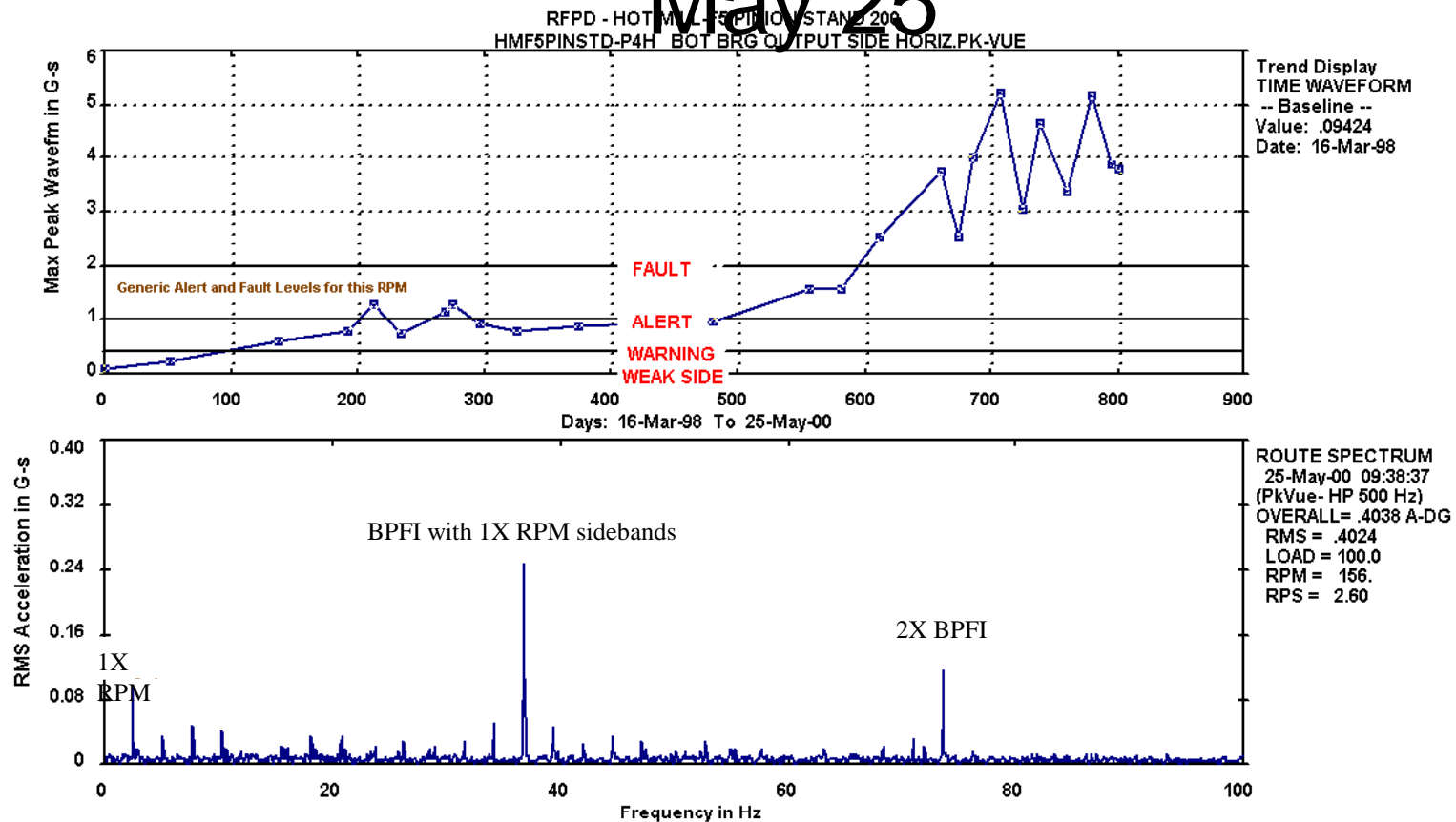
Impacting Sporadic



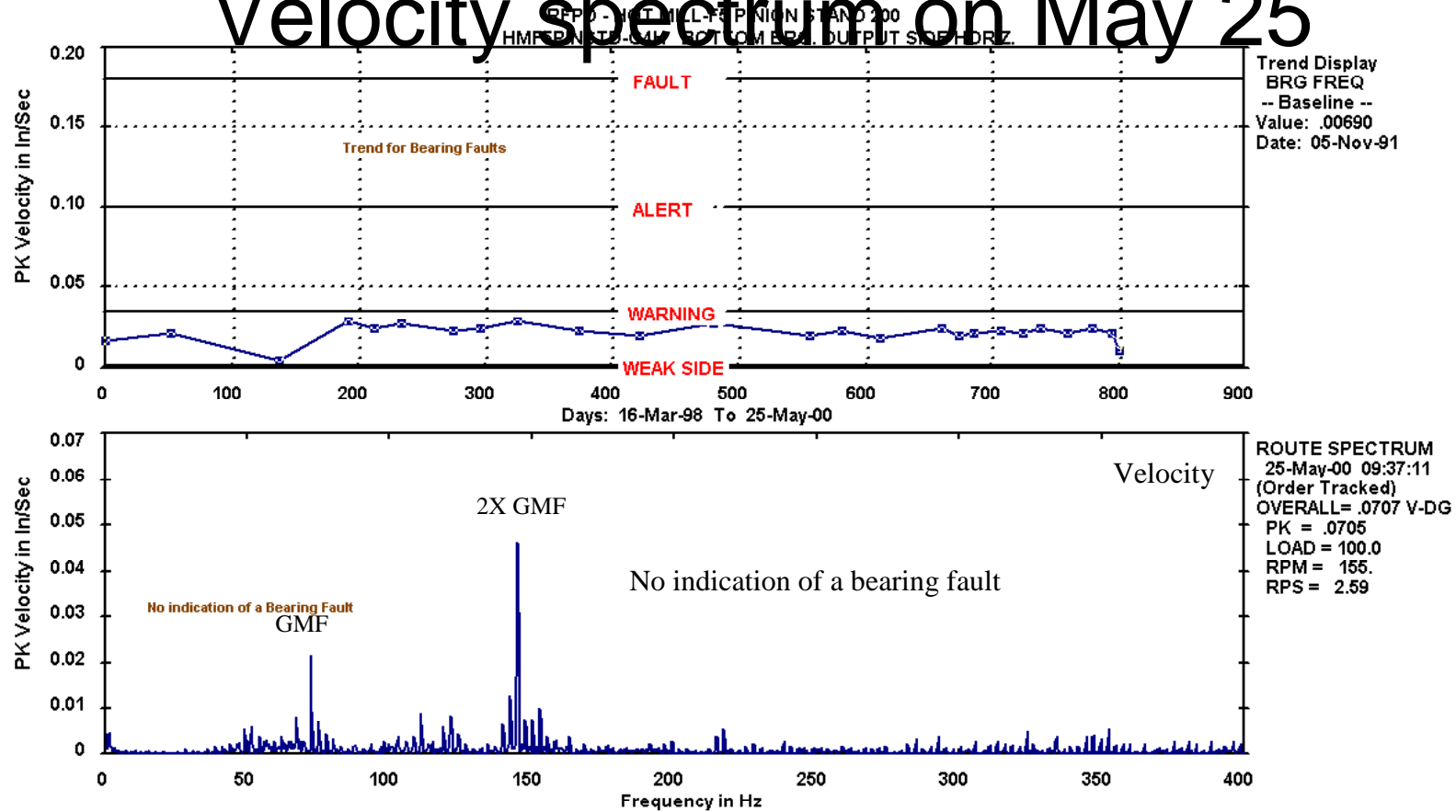
Bearing (Inner Race)

- Case Study #6
 - **BPFI on bearing on output shaft**
 - **Severity ascertained from trending**

Trend (2 years) of the maximum peak amplitude (g's) from the Peakvue waveform and a Peakvue spectrum on May 25



Trend (2 years) of the bearing frequency band from the velocity spectrum and a Velocity spectrum on May 25

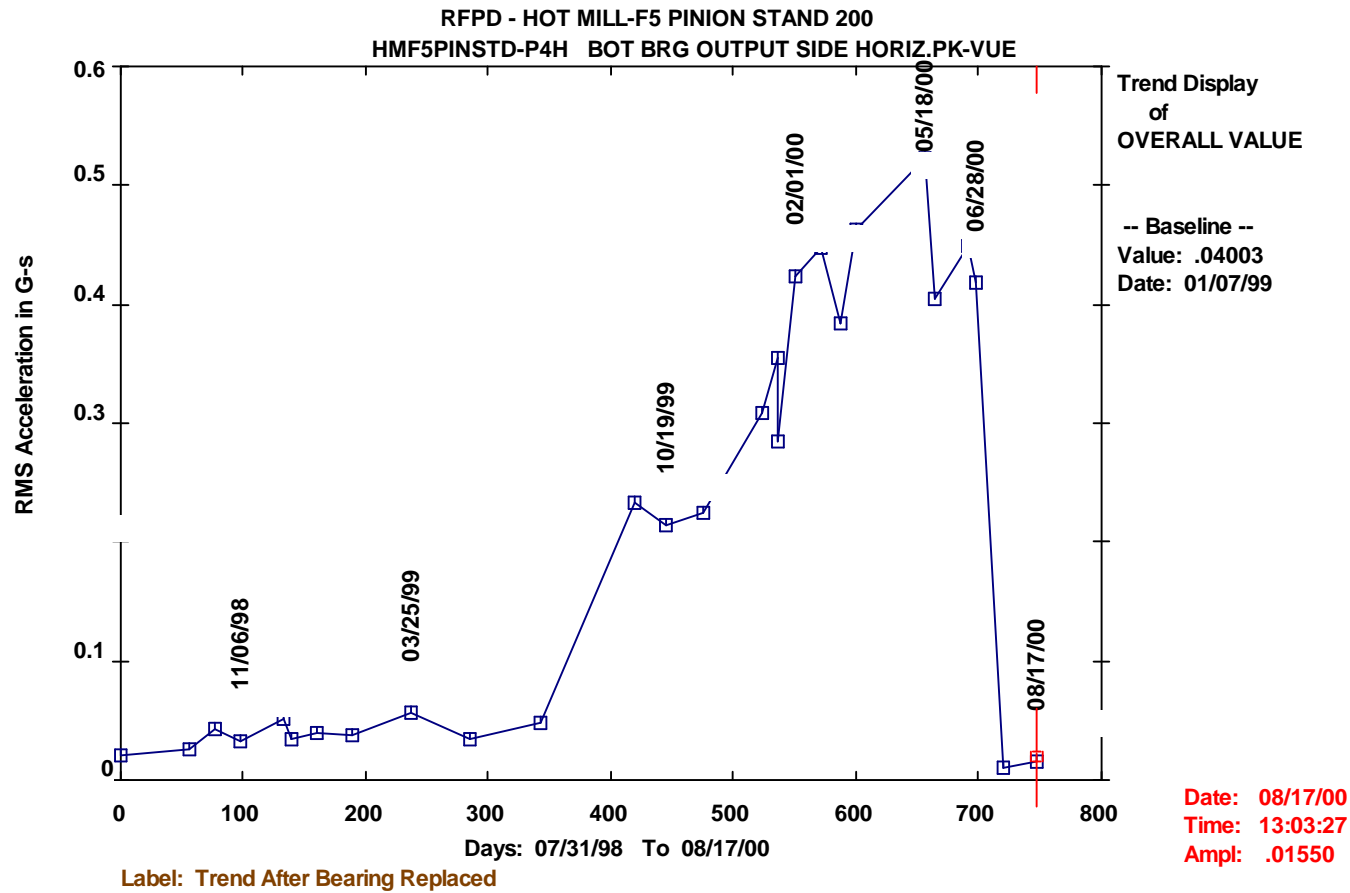


Picture of the defective bearing with a significant inner race defect identified by Peakvue trends



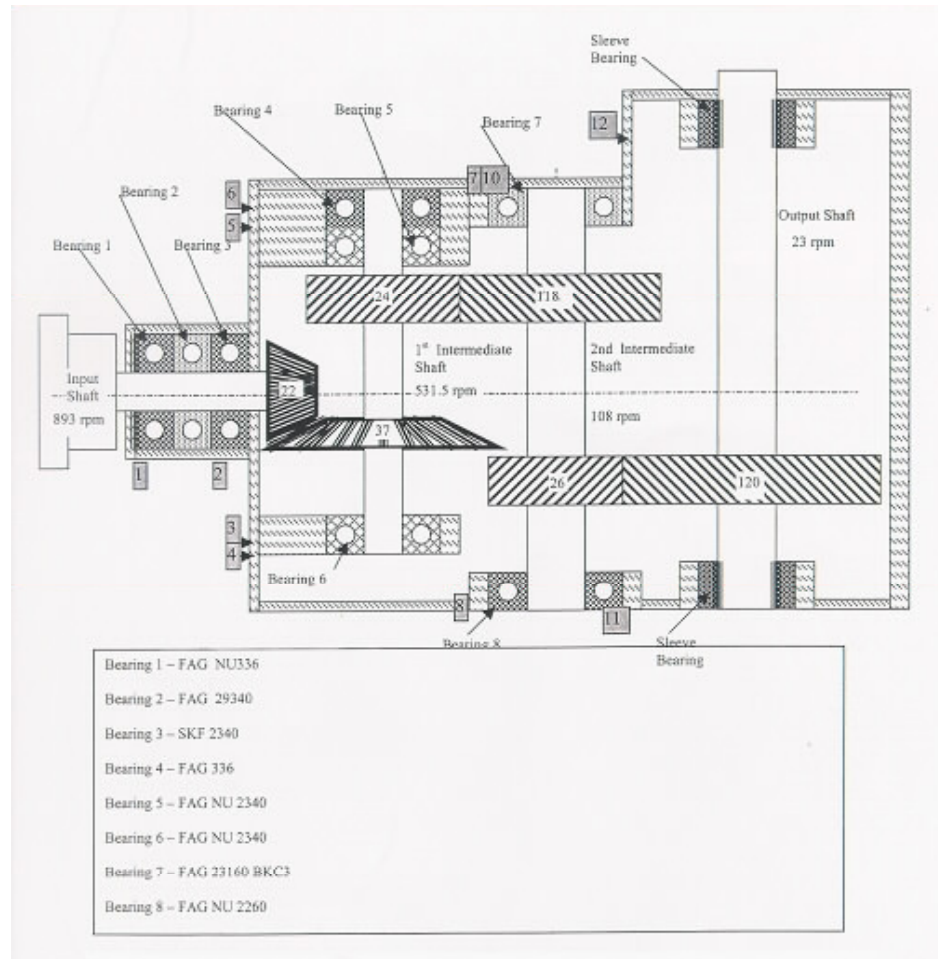
PeakVue Trend Before & After Bearing was Replaced

(Trend of Digital Overall)

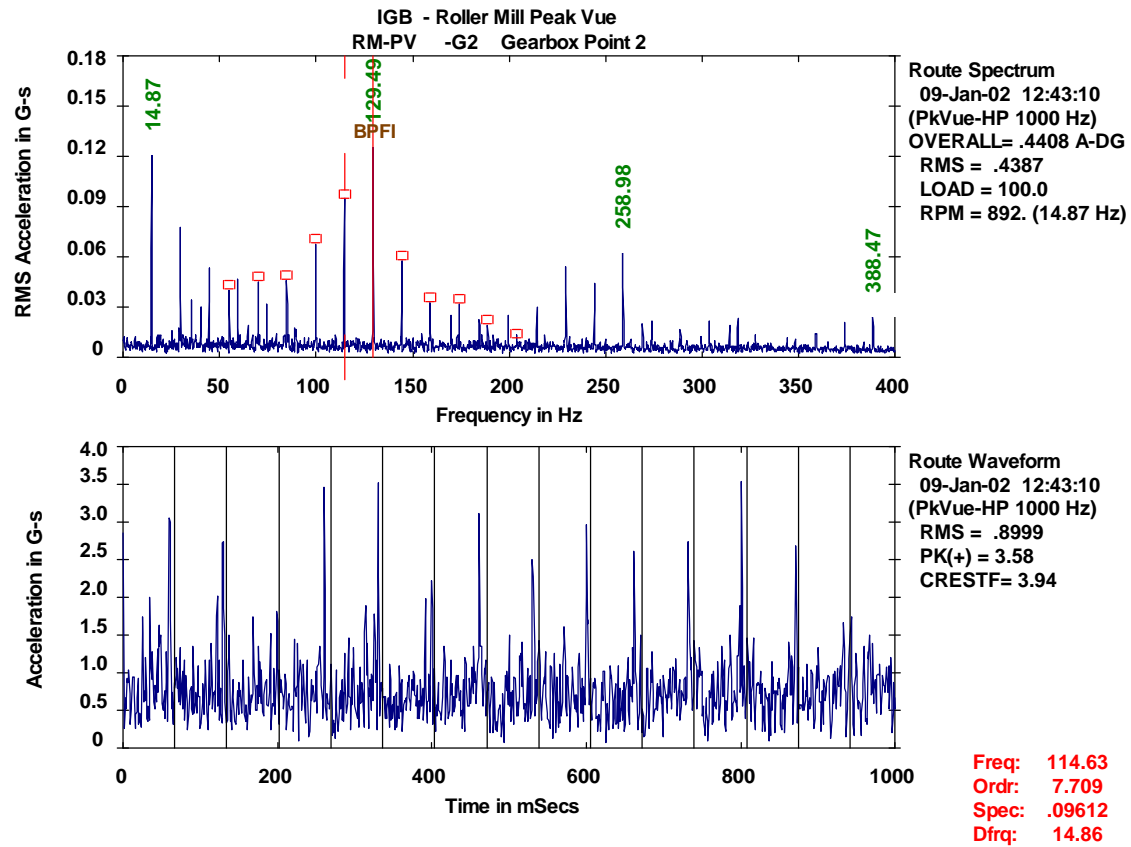


Bearing Inner Race

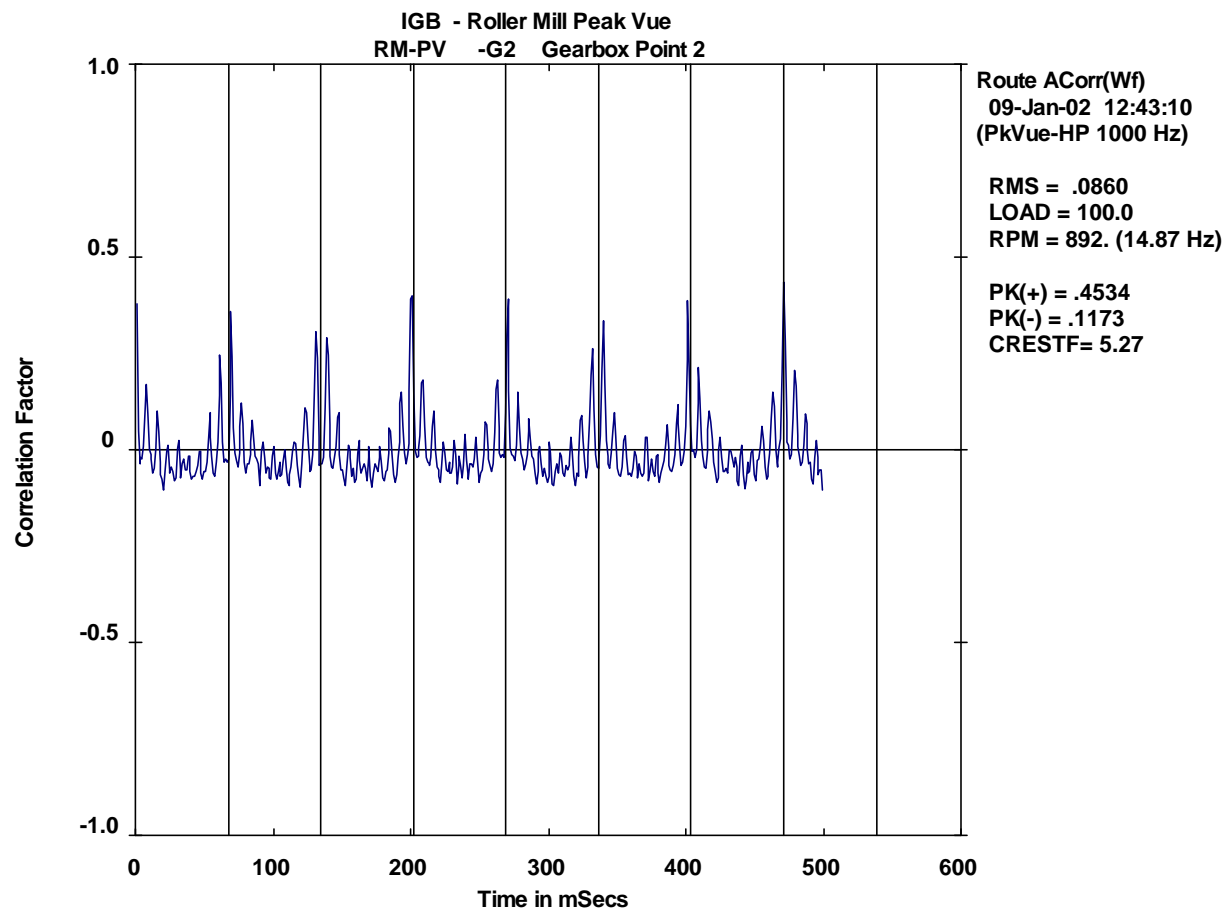
- Case Study # 7
 - **BPFI (mechanical plus lubrication)**



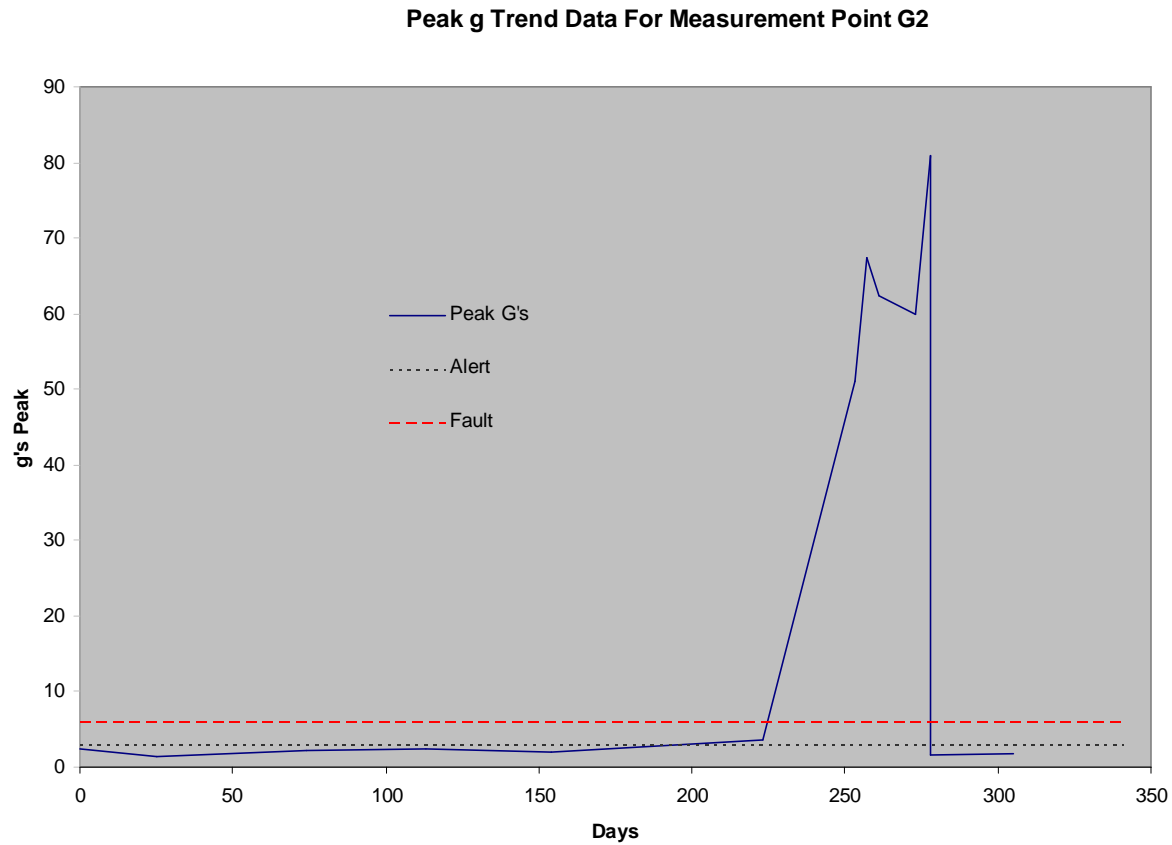
Data acquired outer bearing re input



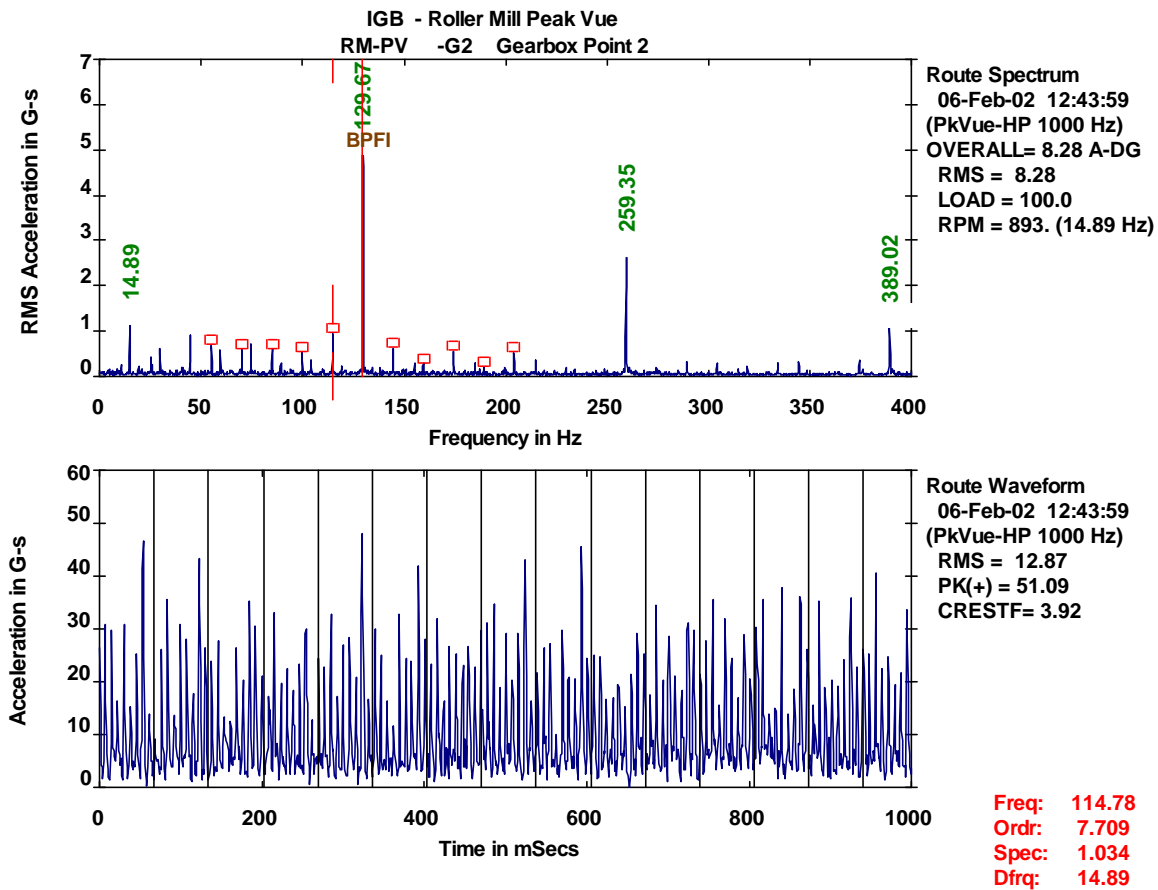
Typical BPF1 pattern in Autocorrelation



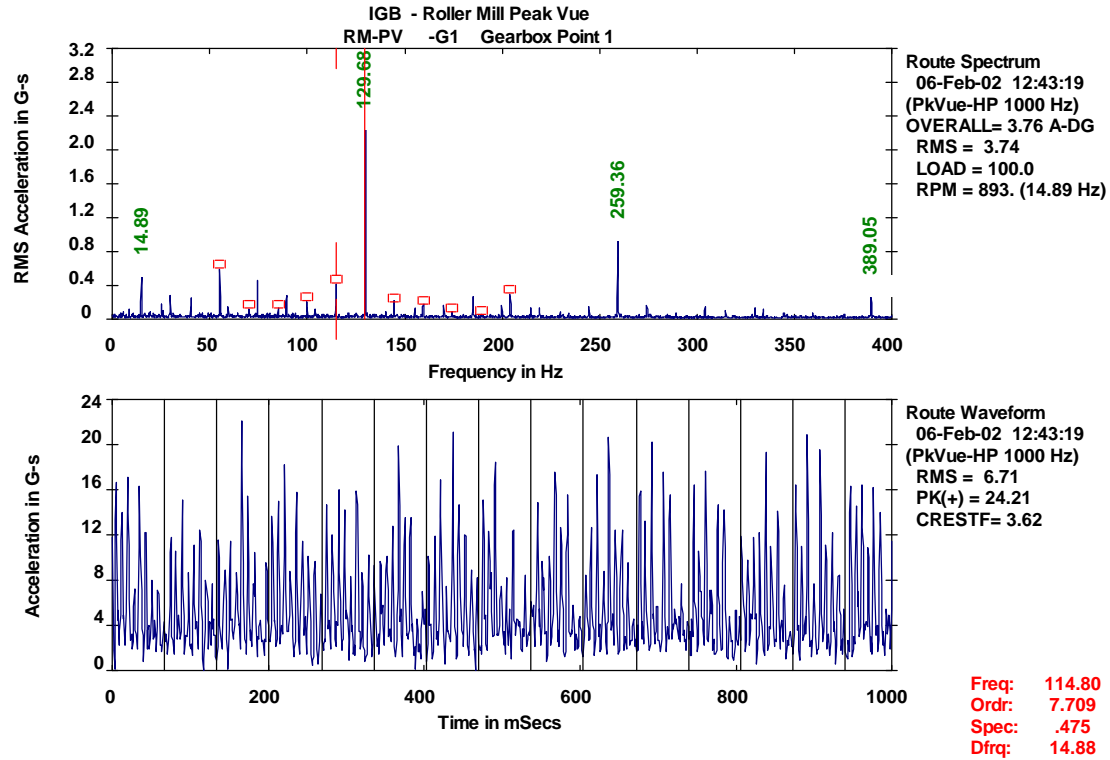
Trended Peak g-level from G2



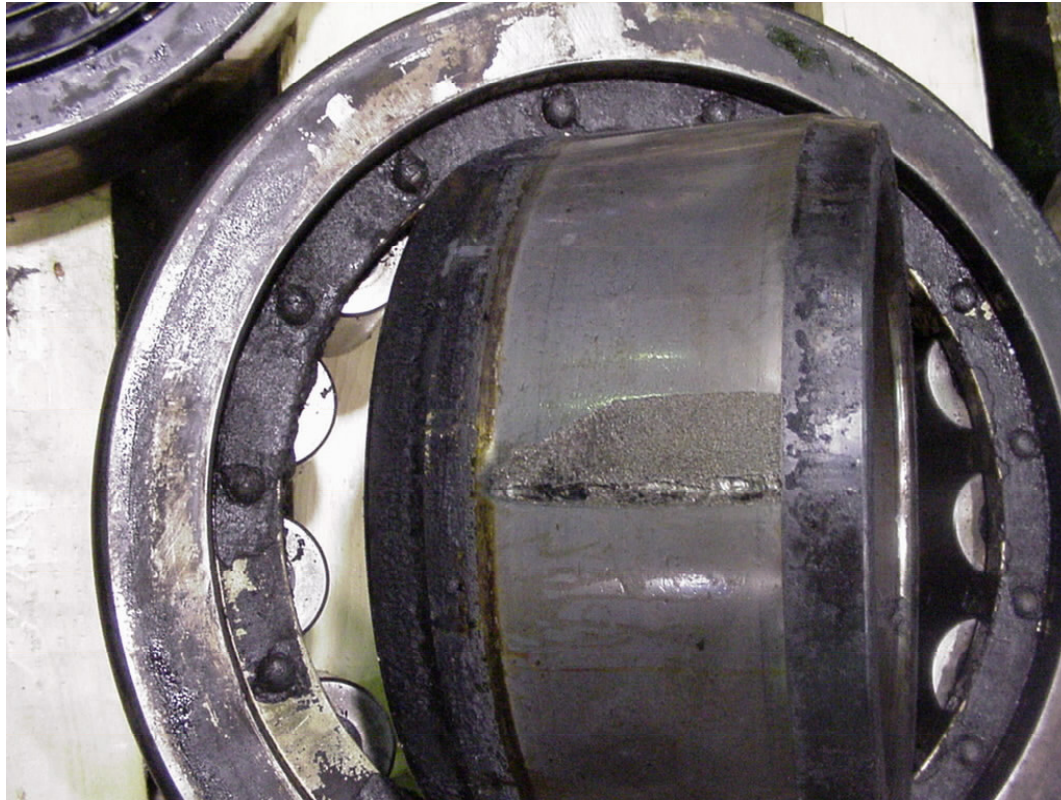
51 g's on Point G2 on February 6, 2002



25 g's on Point G1 on February 6, 2002.



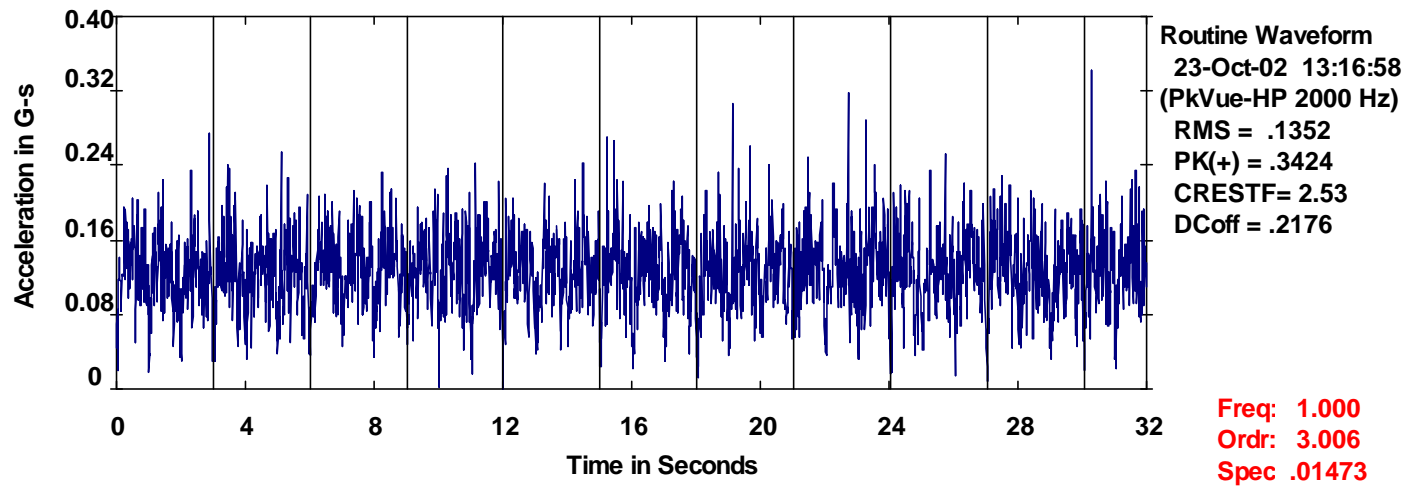
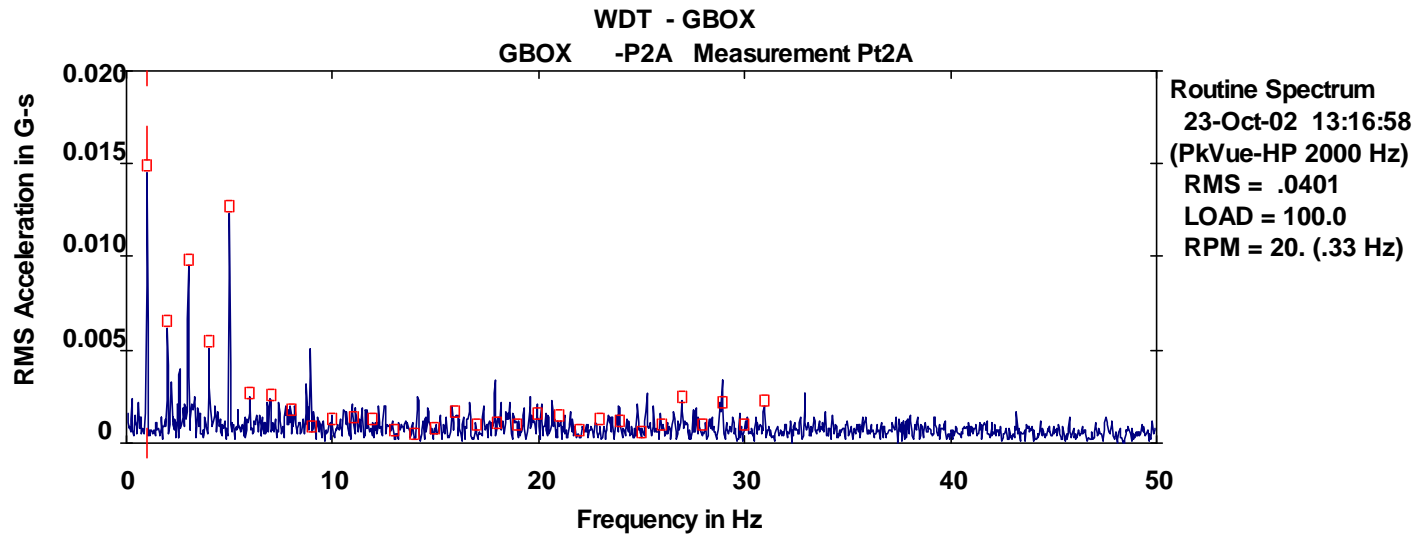
Note metal removal on inner race downstream of fault



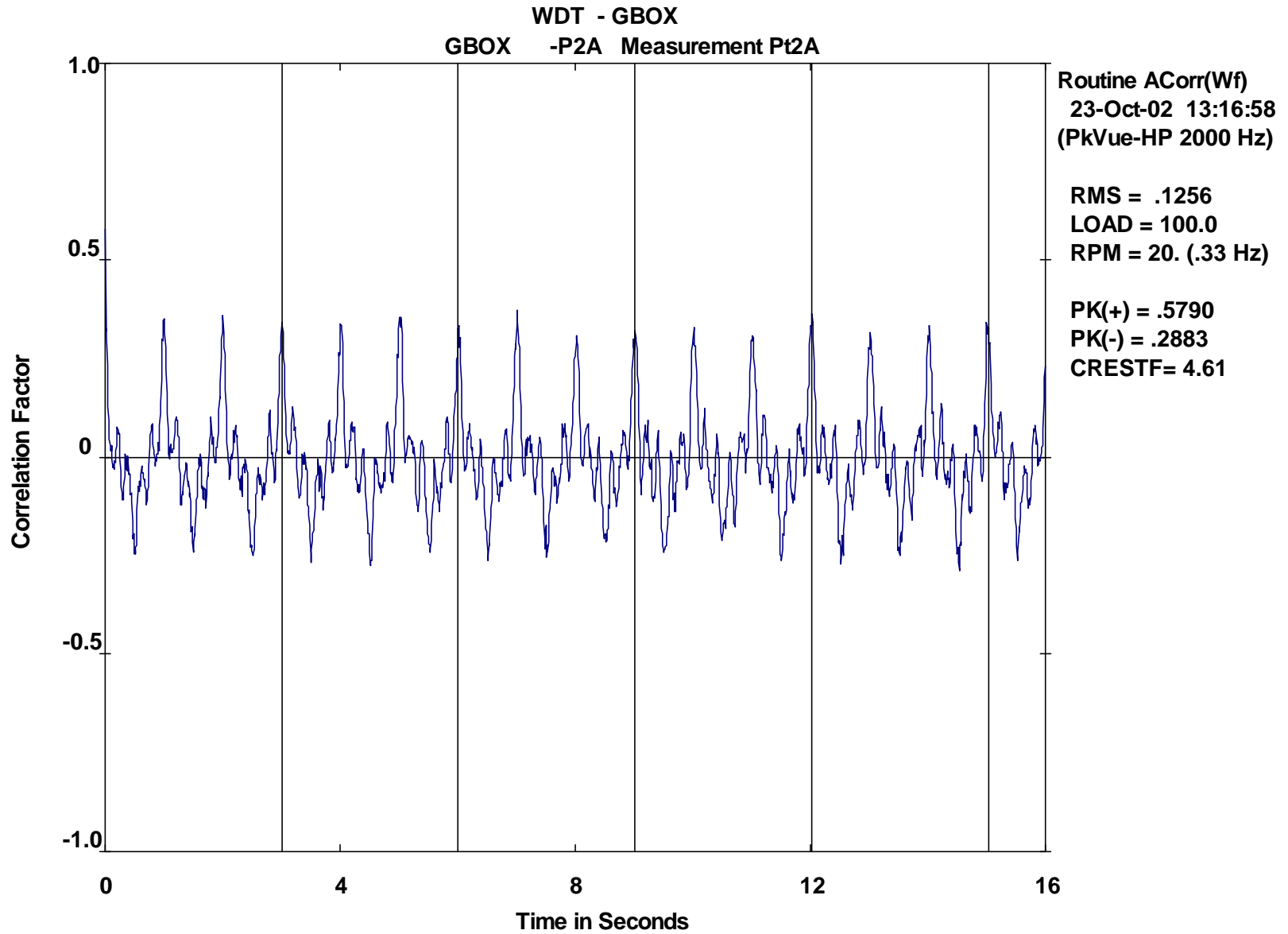
Gear Fault in Planetary Gear

- Planetary Gearbox
- Carrier turning at approximately 20 RPM

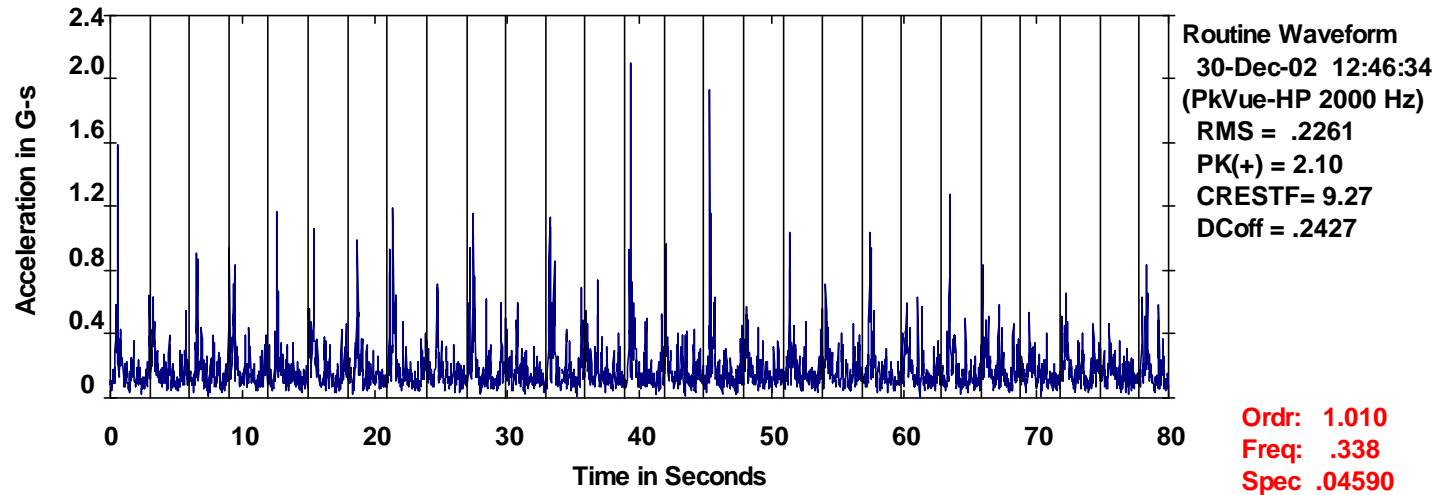
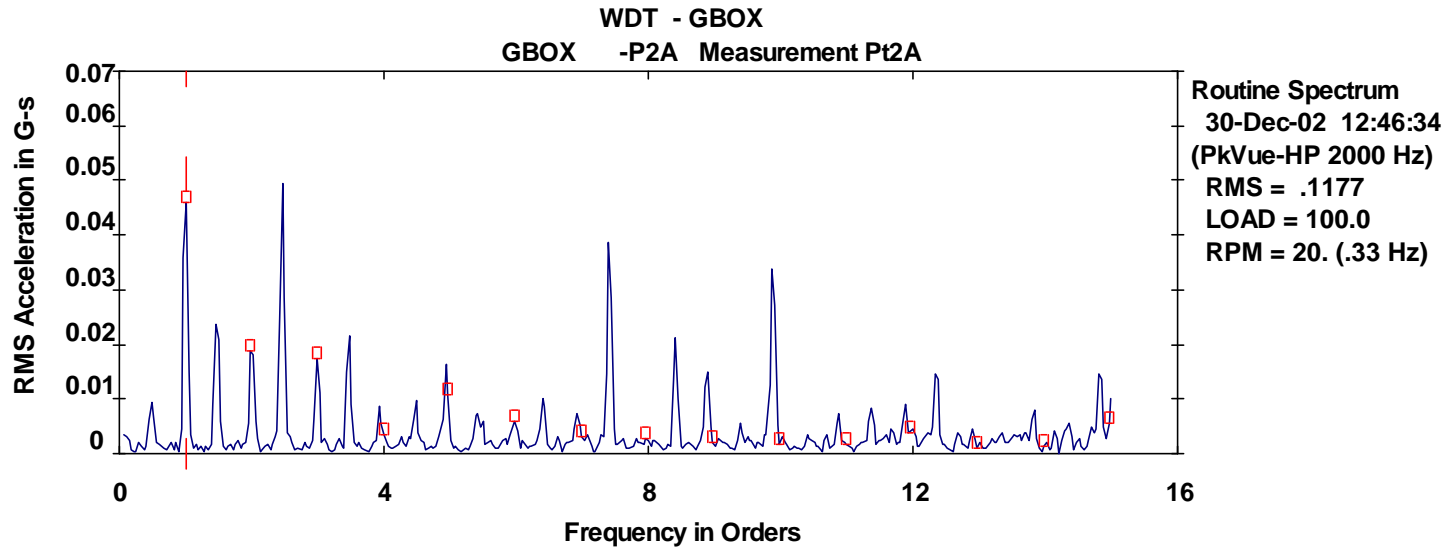
Dominant activity at 3x: 0.34 g's on October 23, 2002



Autocorrelation on October 23, 2002

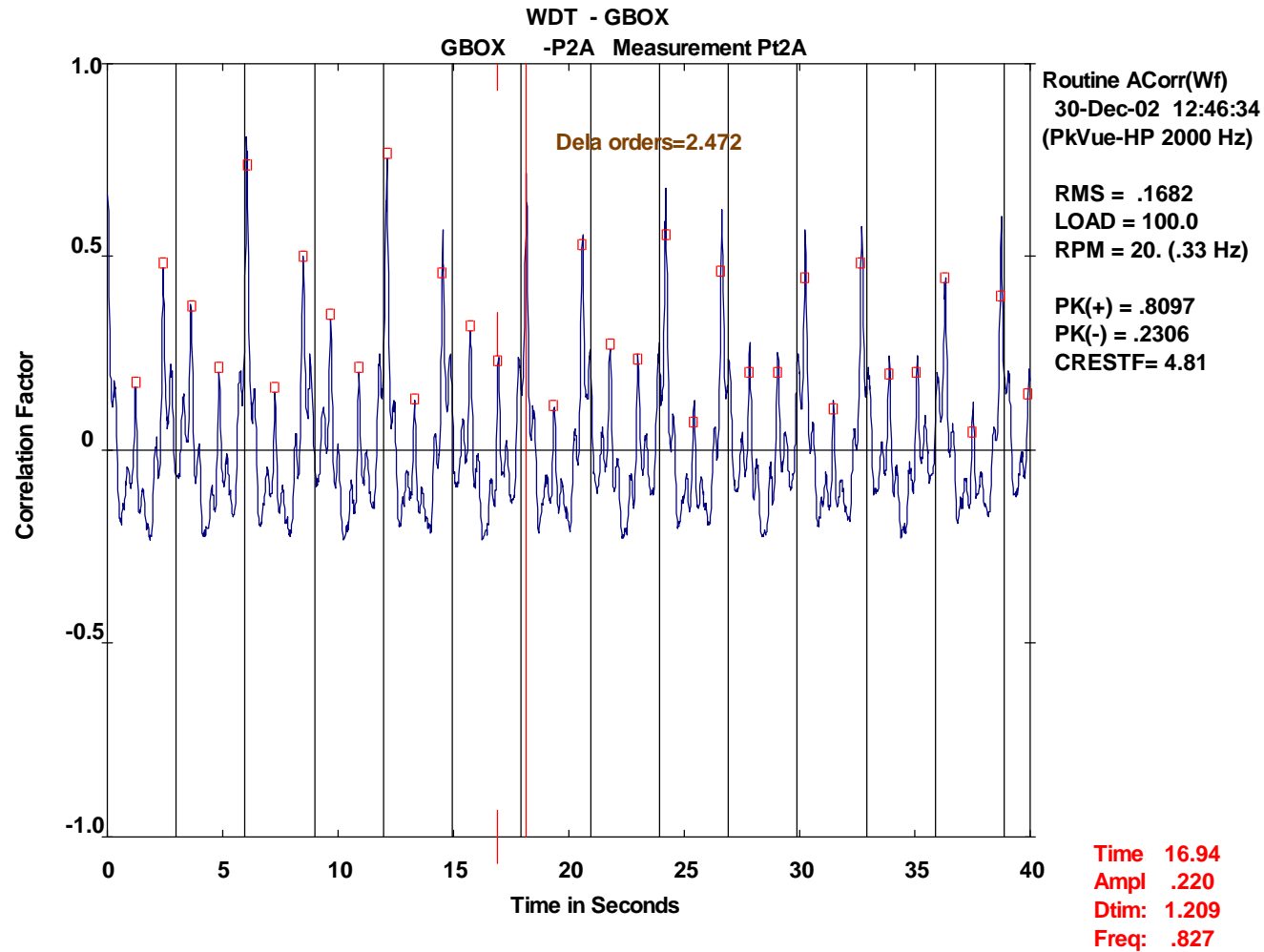


Dominate activity at 1x: 2.1 g's on December 30, 2002

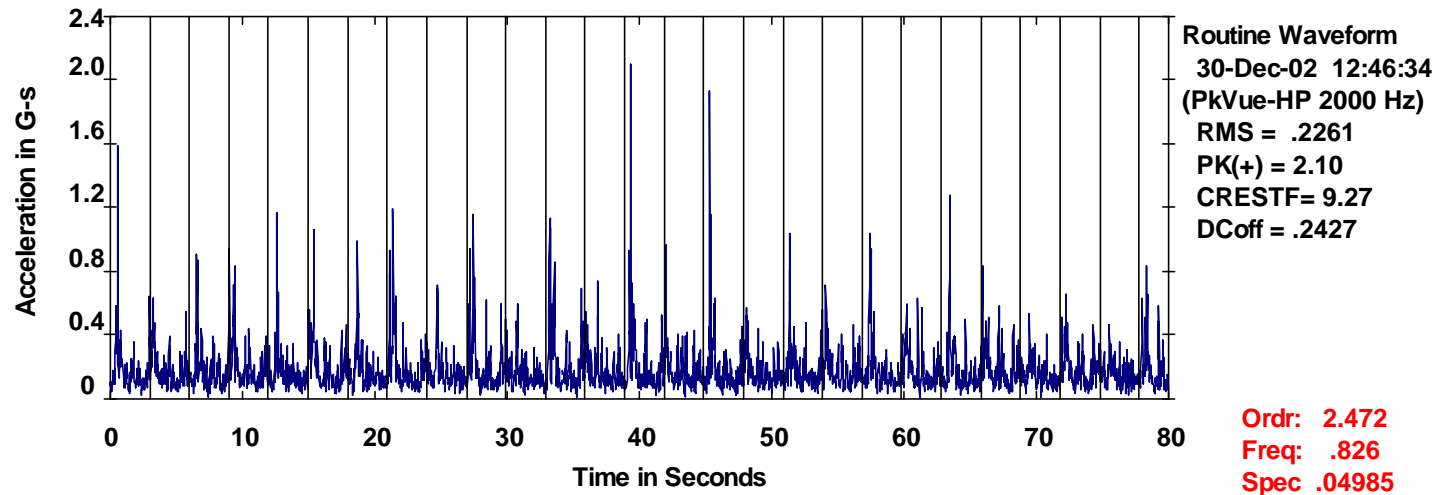
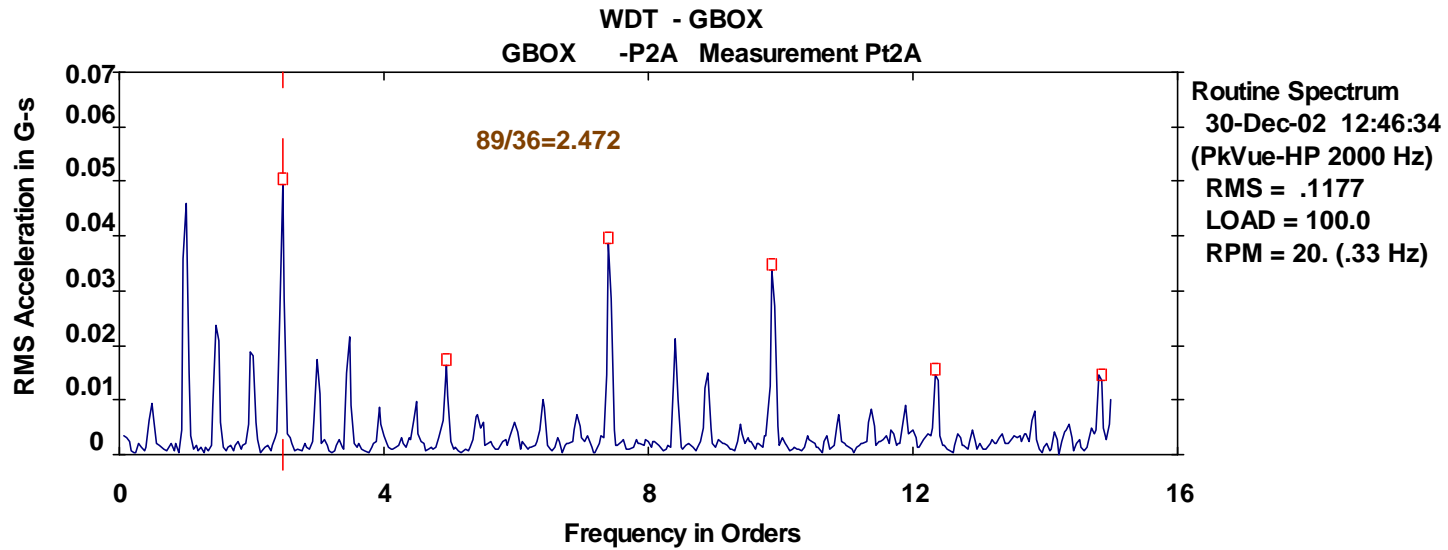


Autocorrelation on December 30, 2002

Dominate activity at 2.47 orders



Activity Highlighted at 2.47 Orders



2.47 activity gone on February 3, 2003

Dominant activity at 3x: 0.75 g's

